Understanding martensite and twin formation in austenitic steels: a model describing TRIP and TWIP effects

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Abstract

A unified description for the evolution of ϵ - and α' - martensite, and twinning in austenitic steels is presented. The formation of micron—scale ϵ and twin bands is obtained by considering the evolution of hierarchically arranged nano-sized ϵ and twins (embryos). The critical size and applied stress when these structures form is obtained by minimising their free energy of formation. The difference between forming an ϵ plate or a twin lies in the number of overlapping stacking faults in their structure. A nucleation rate criterion is proposed in terms of the critical embryo size, resolved shear stress and embryo number density. Based on Olson and Cohen's classical α' -martensite transformation model, the nucleation rate of α' is considered proportional to that for ϵ . These results, combined with dislocation-based approximations, are employed to prescribe the microstructure and flow stress response in steels where transformation-induced-plasticity (TRIP) and/or twinning-inducedplasticity (TWIP) effects operate; these include austenitic stainless and high–Mn steels. Maps showing the operation range of ϵ , α' and twinning in terms of the stacking fault energy at different strain levels are defined. Effects of chemical composition in the microstructure and mechanical response in stainless steels are also explored. These results allow identifying potential compositional scenarios when the TRIP and/or TWIP effects are promoted in austenitic steels.

Keywords: Austenite; Martensite; Deformation twinning; TRIP-assisted steel; Modelling

1 Introduction

Mechanical properties of austenitic steels depend strongly on the stability of the matrix. High strength, ductility and toughness can be achieved via the TRIP (transformation– induced plasticity) or TWIP (twinning–induced plasticity) effects where, respectively, strain-induced martensite and mechanical twinning form to accommodate additional strain. The occurrence of these mechanisms depends on the stacking fault energy (γ_{SFE}), the initial microstructure and deformation conditions [1, 2]; martensitic transformation from austenite (γ) to ϵ -martensite and/or α' -martensite occurs if γ_{SFE} is typically below 20 mJ m⁻², whereas mechanical twinning is promoted if the stacking fault energy lies between 15 and 30 mJ m⁻². It has been reported that these structures form simultaneously if γ_{SFE} lies between 15 and 20 mJ m⁻². For instance, Shen *et al.* [3] reported that ϵ , α' and twinning operate in 304SS ($\gamma_{SFE} = 18 \text{ mJ m}^{-2}$) at different strains; ϵ and twinning act as intermediate phases in the transformation from γ to α' -martensite. Analogous results have been obtained by other authors in steels with similar γ_{SFE} values [4–6]. The reason for their simultaneous operation is that the mechanisms of formation and evolution of ϵ and twins are in fact similar [7]. ϵ -martensite forms by the arrangement of intrinsic stacking faults on every second $\{111\}$ plane, whereas twins form by overlapping three stacking faults on successive planes [8]; stacking faults typically form by the dissociation of $\frac{1}{2}\langle 110\rangle \{111\}$ dislocations into $\frac{1}{6}\langle 112\rangle \{111\}$ Shockley partials. However, other authors have reported in C-containing TWIP steels possible twin formation by the formation of Frank partials [9]. The structure of ϵ -martensite is different from the HCP phase in Fe forming at high pressures [10]; in the former, the structure consists of closely spaced stacking faults (deformation bands) within the matrix, whereas in the latter less microstructural defects have been observed, exhibiting a nearly uniform hexagonal structure. α' -martensite forms at the intersections of deformation bands (ϵ martensite or twins) and its growth is confined to the extent of the bands [11]. Talonen and Hänninen [12] showed that α' formation is also strongly influenced by the stacking fault energy.

Several models describing the evolution of ϵ/α' martensite [13–15] and twinning [16] and their effect on mechanical properties have been proposed. These formulations are based on considering a single mechanism (TRIP or TWIP) and there are few physics-based approximations considering both effects simultaneously as a function of the stacking fault energy. Dini *et al.* [17] used artificial neural networks to predict the mechanical response of Fe–Mn–Si–Al when TRIP and TWIP effects are present, however no microstructural information was included. Latypov *et al.* [18] have combined the finite–element method with phenomenological descriptions for dislocation, twinning and martensite evolution in a multiphase steel; although they were able to describe the strain hardening response and relative strain partitioning, no information on the effects of stacking fault energy in twinning or α' formation were considered. This shows that, although these formulations are able to reproduce the behaviour of the evolving microstructures and mechanical properties, their application is valid only for specific alloying conditions (*e.g.* stacking fault energy). One of the reasons for this is the lack of a single framework being able to predict the occurrence and evolution of ϵ , α' and twinning, hence dictating the transitions where these structures operate.

The objective of this work is to introduce a unified description of ϵ - and α' - martensite, and twinning in austenitic steels. It is based on postulating a mechanism for the formation of (micro) ϵ and twin bands being composed by hierarchical sequences of nano-sized ϵ and twins (embryos); the free energies for ϵ and twin formation are expressed in terms of the embryo width, stacking fault energy and applied stress in Section 3; the only difference between these energies is the number of stacking faults required for their nucleation. This allows determining the critical width of a stacking fault acting as nuclei for ϵ and/or twins. A nucleation rate criterion is proposed in terms of the critical width, resolved shear stress and number density of the nano structures. Based on Olson and Cohen's classical transformation model [19], the nucleation rate of α' is considered proportional to that for ϵ . These results are combined with dislocation-based descriptions to describe microstructure and flow stress where both TRIP and TWIP effects operate (Section 4). The model results are applied to various stainless and high–Mn austenitic steels in Section 5, predicting successfully the relative contribution to work hardening when more than one mechanism operates. Maps showing the operation range of ϵ , α' and twinning in terms of the stacking fault energy at different strain levels are shown in Section 6. Effects of chemical composition in the microstructure and mechanical response are also explored in this section. Concluding remarks are highlighted in Section 7.

2 Materials

A number of stainless and Mn containing austenitic steels have been studied in this work. Table 1 shows their chemical composition and commercial denomination. Experimental results on the microstructure and mechanical response were obtained from the literature. For the case of 301SS and 304SS, a number of alloys were explored with different chemical compositions; specific compositions for each case will be provided throughout the manuscript.

3 Theory

3.1 ϵ martensite and twin formation

 ϵ -martensite and twins form to accommodate excess strain from external loading. Previous experimental and theoretical studies indicate that an embryo of ϵ forms by an intrinsic stacking fault on every second {111} planes [11,20], whereas a twin embryo forms by overlapping three stacking faults on successive planes [8]. Although the interactions of ϵ and twins with the matrix and other crystal defects may differ, experimental evidence shows that their mechanisms of formation and evolution are in fact similar [7]. Fujita and Ueda [20] studied the mechanism of ϵ formation in Fe-18Cr-9.5Ni-1.5Mn-0.65Si-0.06C (wt %) finding that ϵ plates grow by overlapping stacking faults on {111} planes on every two atomic layers; they also found that once a stacking fault forms, adjacent faults can be easily activated promoting the growth of ϵ bands. More recently, Martin *et al.* [21] explored in detail the structure of ϵ -martensite in a stainless steel with composition Fe-15Cr-6Mn-6Ni-1Si-0.01C (wt%) and stacking fault energy equal to 17.5 mJ m⁻². Using high-resolution TEM, they observed that deformation bands (ϵ +twins) of several hundred nanometres were composed by periodic arrangements of stacking faults with less than 10 nm in thickness. They also observed a continuum transition between microstructural features where no sharp interfaces formed between ϵ and γ . Other authors have found similar arrangements of periodic nano-sized structures within ϵ bands [3]. Wei et al. [22] observed similar structures in a TWIP steel with composition Fe–28.64Mn–0.6C (wt%); the stacking fault of this steel is in the range 20–30 mJ m⁻². They reported that a

micron–scale twin is composed by a hierarchical structure of overlapping nano–sized (6–8 nm) twins of constant width and clean boundaries, *i.e.* dislocation–free. Additionally, they found that not only the density of twins increases with strain but also their average width; the latter increases by overlapping additional nano–twins. Similar hierarchical structures of nano–twins have been observed by other authors [23].

These results indicate that the structures of micro- ϵ and twin bands consist of hierarchically arranged periodic sequences of nano-sized structures (embryos) and the bands grow by overlapping additional embryos. Following Fujita and Ueda's [20] analysis on ϵ martensite formation, the following mechanism is proposed for both ϵ and twin formation: i) an isolated stacking fault of width r_i forms on a {111} plane from the dissociation of a perfect dislocation under an applied stress (and positive strain rate $\dot{\varepsilon} > 0$), as schematically illustrated in Figure 1(a). ii) The size of the stacking fault increases with applied stress until reaching a critical width r_i^* (Figure 1(b)); the thickness t_i of a stacking fault is typically 100 nm [3,12]. *iii*) A number of stacking faults n_i ($n_{\epsilon} = 1$ [24] and $n_t = 3$ [8]) overlap in adjacent {111} planes to form an embryo with a critical width r_i^* and length l_i^* ; this process aids in reducing the excess stress concentration from dislocation pile-ups [22]; this arrangement is schematically shown in Figure 1(b) for the case of an ϵ embryo and in (c) for a twin. iv) The length of the embryo l_i increases and propagates through the grain interiors by subsequent overlapping of stacking faults in adjacent planes (Figure 1(d)). v) Once the structure has fully formed, its width w_i increases by forming adjacent embryos of constant width r_i^* , as shown in Figure 1(e); this gives $w_i = r_i^* \hat{N}_i$, where \hat{N}_i is the number of embryos in a band. vi) The increase in ϵ /twinning volume fraction increases by the formation and overlapping of new embryos in various locations of a grain leading to the formation of micro-bands (Figure 1(f)). The critical width to form a nano-sized embry
o r_i^\ast and the nucleation rate are required to describe microstructure evolution. The former can be estimated when a critical value for the energy of formation is reached and it depends on the stacking fault energy [19].

Kibey *et al.* [8] showed that the free energy of a twin embryo is composed by *i*) the strain energy of overlapping partials forming the nucleus, E_{dis} ; *ii*) the energy associated

with the nucleation of an embryo, E_{emb} ; and *iii*) the work done by the applied stress τ aiding in forming the stacking faults: $E_{\tau} = \frac{1}{m_{SF}} \tau b r_i^2 n_i$ [8], where r_i is the width of a stacking fault (forming embryo), n_i is the number of stacking faults in an embryo, b = 0.25 nm is the magnitude of the Burgers vector and m_{SF} is the Schmid factor of a partial forming in the $\langle 112 \rangle \{111\}$ system. It is assumed that this analysis applies also to ϵ formation. The energy associated with stacking faults overlapping can be approximated by the energy of a pile–up [8]: $E_{dis} = \frac{n_i^2 \mu b^2}{8\pi (1-\nu)} r_i \ln\left(\frac{r_i}{2n_i l_i}\right)$, where $\mu = 70$ GPa is the shear modulus and $\nu = 0.31$ is Poisson's ratio; in this case $l_i^* = n_i b$ when $r_i = r_i^*$ (Figures 1(b) and (c)). Olson and Cohen [19] proposed that the energy for stacking fault nucleation (per unit area) is the difference between the stacking fault energy in the faulted planes $(\gamma_{SFE}n_i)$ and the interfacial energy between the FCC and HCP structure on each stacking fault $2\sigma_{HCP}n_i$ [12, 19]; the energy of formation of an embryo is then $E_{emb} = (\gamma_{SFE} - 2\sigma_{HCP})r_i t_i n_i^{\dagger}$. This equation indicates that if the stacking fault energy is greater than the surface energy, the formation energy for ϵ -martensite is unfavourable and additional dislocation overlapping on successive {111} planes towards forming a twin is preferred. It is worth noting that an area r_i^2 is considered in E_{τ} as the applied stress promotes dislocation dissociation towards forming a stacking fault, whereas the area $r_i t_i$ is considered in E_{emb} as it describes the energy required to form an embryo from an arrangement of existing stacking faults. The free energy is expressed as:

$$E_{i} = E_{dis} + E_{emb} - E_{\tau} = \frac{n_{i}^{2} \mu b^{2}}{8\pi (1-\nu)} r_{i} \ln\left(\frac{r_{i}}{2n_{i}l_{i}}\right) + (\gamma_{SFE} - 2\sigma_{HCP}) r_{i}t_{i}n_{i} - \frac{\tau b r_{i}^{2}n_{i}}{m_{SF}},$$
(1)

where *i* stands for ϵ or t (twin). For the calculations performed in this work, it will be assumed that the loading orientation is [111]; this gives $m_{SF} = 0.31$ [25]. It is interesting noting that if the loading orientation is [001], the Schmid factor is 0.47, and equation 1 shows that the stress required to reach similar E_i values (than for [111]) is higher for this orientation. This is consistent with experimental evidence showing much lower twinning

^{\dagger}Kibey *et al.* defined this energy based on the generalised planar fault energy obtained from *ab initio* simulations. The thermodynamic description of this term is analogous, as it contains the planar energies necessary for stacking fault nucleation.

activity in 316SS under the [001] loading orientation compared to the [111] orientation [25]; similar conclusions have been obtained in Fe-22Mn-0.6C (wt%) [26]. These results show that lower hardening response is expected under [001] orientation as the TRIP/TWIP effects are not favoured.

An embryo forms when a critical width (r_i^*) is reached and the energy E_i is minimised when:

$$\frac{\partial E_i}{\partial r_i} = 0. \tag{2}$$

Using the expressions given in equation 2, it leads to $\frac{\partial E_{dis}}{\partial r_i} = \frac{n_i^2 \mu b^2}{8\pi (1-\nu)} \left(\ln \left(\frac{r_i}{2n_i l_i} \right) + 1 \right)$, $\frac{\partial E_{emb}}{\partial r_i} = \left(\gamma_{SFE} - \sigma_{HCP} \right) r_i t_i n_i$ and $\frac{\partial E_{\tau}}{\partial r_i} = \frac{2\tau b r_i}{m_{SF}} n_i$. Combining these results with equation 2, it gives a relationship between r_i^* , n_i^* and τ to be:

$$\frac{n_i \mu b^2}{8\pi (1-\nu)} \left(\ln\left(\frac{r_i^*}{2bn_i^*}\right) + 1 \right) + \left(\gamma_{SFE} - \sigma_{HCP}\right) r_i^* t_i - \frac{2\pi b r_i^*}{m_{SF}} = 0.$$
(3)

This equation can be solved numerically to obtain r_i^* in terms of τ for a given stacking fault energy. As equation 3 has multiple solutions when τ increases, it is important identifying the critical condition when E_i is minimum; ϵ nucleation is explored initially.

Figure 2(a) shows the possible solutions using equation 3 for ϵ ($n_{\epsilon} = 1$) in a steel with stacking fault energy of 17.5 mJ m⁻² (black solid line); experimental evidence shows that the fraction of ϵ -martensite is higher than the fraction of twins for this condition [3,12]. The surface energy in austenitic steels has been estimated to be in the range 10–15 mJ m⁻² [27,28]; σ_{HCP} =11.5 mJ m⁻² was adjusted for all calculations employed in this work. Experimental estimations of the width of an ϵ embryo are also shown for Fe-15Cr-6Mn-6Ni-1Si-0.01C (wt%) and 304SS obtained from [21] and [3], respectively; the former alloy has the same γ_{SFE} , whereas γ_{SFE} in the latter ranges between 17 and 18 mJ m⁻² [12]. The results show that the critical width increases with stress upon reaching a critical value of $r_{\epsilon}^* = 4.7$ nm when $\tau_{\epsilon}^* = 36$ MPa; lower stress levels are needed at higher widths. Moreover, r_{ϵ}^* corresponds to the size range of the nano– ϵ structures obtained from experiments. In addition, Staudhammer *et al.* [29] estimated an α' embryo width of 5–7 nm in 304SS, being the model results consistent with their findings. To further support these results, Figure 2(b) shows the values of the free energy per unit area (E_{ϵ} is divided by the area $t_{\epsilon}b$) at different stress levels. When $\tau = 0$ MPa (black solid line), E_{ϵ} decreases with low r_{ϵ} , however it increases rapidly as the embryo size increases becoming unstable $(E_{\epsilon} > 0)$. When $\tau = \tau_{\epsilon}^* = 36$ MPa (blue dashed line), the energy reaches a minimum at r_{ϵ}^* and it decreases thereafter, indicating that ϵ growth is stable. When $\tau = 50$ MPa> τ_{ϵ}^{*} (red dotted line), no clear minimum is observed although the energy decreases with embryo size; this suggests that forming a new embryo should be more favourable than increasing its width when the applied stress increases; this is consistent with the proposed mechanism of ϵ formation and growth. It is interesting noting that if $\tau_{\epsilon}^* < \tau_{CRSS}$, where τ_{CRSS} is the critical resolved shear stress (Section 4), stacking faults form during early stages of plastic deformation; this is consistent with Talonen and Hänninen observations in 301LN showing deformation bands forming at low strains [12]. These results indicate that the critical embryo width corresponds to r_{ϵ}^* when the applied stress is τ_{ϵ}^* . In order to compare this result with the critical conditions for twin formation, the solution of the free energy of a twin embryo is also shown in Figure 2(a) (blue dashed line); the critical stress to form a twin is 51 MPa, showing that a higher stress is required for twin formation when $\gamma_{SFE} = 17.5 \text{ mJ} \text{ m}^{-2}$ and ϵ nucleation is more prolific. It is interesting noting that although the experimental measurements of the stacking fault energy can differ slightly, the model is able to capture well the prevailing mechanisms. For instance, if $\gamma_{SFE} = 17$ mJ m $^{-2},$ the critical radius and stress to form an ϵ embryo are 5.3 nm and 29 MPa, respectively, and when $\gamma_{SFE} = 18 \text{ mJ m}^{-2}$, these r_{ϵ}^* and τ_{ϵ}^* are 3.5 nm and 43 MPa, respectively. Similarly for a twin embryo, if $\gamma_{SFE} = 17 \text{ mJ m}^{-2}$ the critical radius and stress are 10.8 nm and 47 MPa, respectively, whereas when $\gamma_{SFE} = 18$ mJ m⁻², r_t^* and τ_t^* equal 8.6 nm and 55 MPa, respectively. In both cases $r_{\epsilon}^* \ge r_t^*$ and $\tau_{\epsilon}^* \le \tau_t^*$ indicating that ϵ formation is more prolific for this range of γ_{SFE} .

The same analysis is followed to study the critical conditions for twin formation when increasing the stacking fault energy; in this case $n_t = 3$ in equations 1 and 3, and a stacking fault energy of 21 mJ m⁻² is considered. Figure 2(c) shows the solution of equation 3 with different stress values (blue solid line). Experimental estimations on the thickness of a nano twin are also shown for Fe-24Mn-0.6C with γ_{SFE} to be within this range [22]. It is also observed that the critical width $r_t^* = 6$ nm at the maximum stress ($\tau_t^* = 86$ MPa) is very close to the values obtained experimentally. Moreover, similar trends are obtained when plotting the variations of the free energy per unit area ($E_t/(t_t b)$) with stacking fault width in Figure 2(d): it is only at r_t^* when $\tau = \tau_t^*$, that the free energy reaches a minimum value (dashed line). This also confirms that r_t^* should be the critical width of a nano-twin forming once the applied stress is τ_t^* . In order to compare the conditions between twin and ϵ formation for this γ_{SFE} , the free energy of an ϵ embryo is also shown in Figure 2(c) (black dotted line); it is observed that much higher stress levels are required before an ϵ embryo can form (143 MPa), indicating that twin formation is more favourable in this case.

These results show that the width of nano-scaled ϵ and twins can be prescribed using the same energy balance and their occurrence differs by the number of stacking faults required to form each structure. Equation 3 shows that the applied stress to form an embryo increases with increasing the stacking fault energy. This indicates that for steels with low stacking fault energy lower applied stress levels are required to form a stacking fault; hence a lower dislocation density is needed, increasing the probability of forming an isolated stacking fault (ϵ embryo). Conversely, if the stacking fault energy increases, higher dislocation density is promoted with increasing applied stress; this results in a higher probability for stacking fault/dislocation interactions promoting the formation of nanotwins. The relative contribution and competition between each mechanism are explored in detail in Section 6. It is worth mentioning that other dislocation dissociation reactions have been reported to influence twinning in TWIP steels containing high carbon additions [9]; this is due to the increase in local stress concentrations promoted by interstitial carbon atoms [25, 30]. This is not considered in the present model to simplify the analysis, as a link between local stress concentration and carbon content would be needed in equation 1. Possible extensions to the model to include this are explored in the Discussion section. The results obtained in this section will allow describing the conditions for α' martensite formation in terms of ϵ bands.

3.2 α' martensite formation

It is well established that α' -martensite nucleates at the intersections of deformation bands in metastable austenitic steels. The growth of α' plates occurs by the repeated nucleation and coalescence of new α' embryos [31]; this mechanism is analogous to that proposed for ϵ in the previous Section. Deformation bands can be composed by ϵ -martensite and twins. It has been argued that α' forms only in steels with stacking fault energy below ~ 20 mJ m⁻² [2], however van Tol et al. [32] have observed small fractions of $\alpha' \ (\leq 1.2\%)$ in a TWIP steel during deep drawing; the stacking fault energy calculated for this steel was 50 mJ m⁻². As the fraction of α' is very low for this steel with high-stacking fault energy, it will be assumed that ϵ is the main precursor for the $\gamma \to \alpha'$ transformation under uniaxial loading [3]. This is also supported by experiments showing that α' and ϵ have the same dependence in the stacking fault energy [12]: as γ_{SFE} increases, the overlapping of stacking faults becomes more irregular, and the nucleation of the α' martensite becomes more difficult. Moreover, it was shown in the previous section that the width of an ϵ embryo is in the same width range than α' embryos estimated experimentally [29]. Thus, it can be assumed that α' forms from ϵ embryos and that the nucleation rate of α' is linked to ϵ formation; this gives the size of an α' embryo to be $r_{\alpha'}^* = r_{\epsilon}^*$ and $t_{\alpha'} = t_{\epsilon} = 100$ nm when $\tau_{\alpha'}^* = \tau_{\epsilon}^*$.

In Olson and Cohen's model for α' transformation [11] it was assumed in the nucleation rate of α' embryos is proportional to the nucleation rate of ϵ bands, $\frac{dN_{\alpha'}}{dt} = p \frac{dN_{\epsilon}}{dt}$, with pbeing the probability of nucleating an embryo from the intersection. They assumed that p was controlled by the temperature and stacking fault energy, however since these effects are captured via $r^*_{\alpha'}$, it can be assumed that p is constant. As two intersecting ϵ bands are required to form one α' band, as a first approximation, the nucleation rate of α' is proposed to evolve at half the rate of ϵ , leading to:

$$\frac{dN_{\alpha'}}{dt} = \frac{1}{2}\frac{dN_{\epsilon}}{dt}.$$
(4)

This result will enable prescribing ϵ and α' within the same formalism. Complete mi-

crostructure evolution is presented in the following section.

3.3 Microstructure evolution

The critical size to form an embryo of ϵ , α' and twin were obtained in terms of the stacking fault energy and applied stress. In order to prescribe the evolution of these features, the nucleation rate $\frac{dN_i}{dt}$ and size of each structure are required. In the latter, r_i^* and t_i are constant and only their mean length is needed.

An evolution equation for the mean twin length (l_i) with strain has been obtained in hexagonal closed-packed metals [33]. This was done by estimating the variation of l_i with strain at the grain level, showing that it depends only on the nucleation rate of new embryos, as illustrated in Figure 1(d); the equation equals:

$$\frac{dl_i}{d\varepsilon} = \frac{1}{N_i} \frac{dN_i}{d\varepsilon} (D - l_i), \tag{5}$$

where D is the average grain size, N_i is the number density of nano-structures and $\frac{dN_i}{d\varepsilon}$ is the nucleation rate variation with axial strain; this equation is considered to be valid also for ϵ and α' , as it depends only on the nucleation rate for a given grain size.

In order to postulate expressions for the nucleation rate of an embryo, it is worth considering the processes affecting their formation, namely [33]: 1) Dislocation dissociation towards forming arrangements of stacking faults requires the formation and glide of n_i perfect dislocations (Figure 1(a)); this process can be accounted for by considering the ratio $\frac{\tau_{nuc}}{n_i \tau_{CRSS}}$, where τ_{nuc} is the stress required to nucleate a dislocation (also referred to as friction stress) and τ_{CRSS} is the critical resolved shear stress to move that dislocation; the latter depends on composition, grain size and deformation conditions. 2) Increasing the width (r_i^*) and number density (N_i) of embryos will increase the frequency of dislocation pile–ups promoting the formation of new embryos [24]; this also promotes the formation of secondary deformation bands/twins on secondary slip planes [2]. 3) The number of nano–structures is limited by the volume fraction of the respective crystal defect. The nucleation rate for each structure is proposed in this work to scale with these factors in the phenomenological expression:

$$\frac{dN_{\epsilon}}{dt} = \dot{\varepsilon} \frac{\tau_{nuc}}{\tau_{CRSS}} \frac{r_{\epsilon}^{*}}{bm_{SF}} N_{\epsilon} (1 - f_{\epsilon})$$

$$\frac{dN_{\alpha'}}{dt} = \frac{1}{2} \left(\dot{\varepsilon} \frac{\tau_{nuc}}{\tau_{CRSS}} \frac{r_{\alpha'}^{*}}{bm_{SF}} N_{\alpha'} (1 - f_{\alpha'}) \right)$$

$$\frac{dN_{t}}{dt} = \dot{\varepsilon} \frac{\tau_{nuc}}{3\tau_{CRSS}} \frac{r_{t}^{*}}{bm_{SF}} N_{t} (1 - f_{t}).$$
(6)

Similar expressions have been derived to describe the twin nucleation rate in hexagonal closed packed metals with satisfactory agreement [33]. It is worth noting that $\frac{dN_i}{d\varepsilon} = \frac{1}{\dot{\varepsilon}} \frac{dN_i}{dt}$. Each equation is valid when the applied shear stress equals or exceeds τ_i^* . Since τ_{CRSS} depends on the grain size, composition and deformation conditions (Section 4), equations 6 indicate that martensite and twinning is less likely to occur in fine-grained alloys, as higher stress levels are required for dislocations to propagate and promote stacking fault formation; this is consistent with experimental evidence showing that twin and α' activity decreases with decreasing the grain size [34, 35]. These features, as well as τ_{nuc} and τ_{CRSS} values are explored in the following section. The number of embryos in a deformation band \hat{N}_i defined in Section 3.1 is linked to the number density through the relation $\hat{N}_i = \frac{1}{N_{i,0}} N_i$ [36], where $N_{i,0}$ is the number of nucleation sites. $N_{i,0}$ in classical nucleation theory is assumed to be inversely proportional to the total volume of every single nucleation site [37], which in this case it would be the band limited by $r_i^* t_i D$, as l_i increases up to D (Figure 1(f)); it will be assumed that this relation also holds for the (deformation-controlled) nucleation rate, giving $N_{i,0} = \frac{0.05}{r_i^* t_i D}$, where the 0.05 factor was fitted to adjust all the experimental results tested in this work.

The volume fraction of each structure equals the product of its number density and the volume of an embryo $N_i V_i$; in addition, the term $(1 - f_{\alpha'})$ is added to f_{ϵ} and f_t to account for their reduction when α' increases [3]. This results in the following relations:

$$f_{\epsilon} = N_{\epsilon}V_{\epsilon}(1 - f_{\alpha'}) = N_{\epsilon}r_{\epsilon}^{*}t_{\epsilon}l_{\epsilon}(1 - f_{\alpha'})$$

$$f_{\alpha'} = N_{\alpha'}V_{\alpha'} = N_{\alpha'}r_{\alpha'}^{*}t_{\alpha'}l_{\alpha'}$$

$$f_{t} = N_{t}V_{t}(1 - f_{\alpha'}) = N_{t}r_{t}^{*}t_{t}l_{t}(1 - f_{\alpha'})$$
(7)

Solving equations 6 and 7 allows describing the structure of ϵ , α' and twinning with the same formalism.

4 Dislocation evolution and mechanical response

Prescribing dislocation evolution is necessary to quantify the flow stress response with strain; dislocation activity in the γ is affected when the fraction of ϵ and α' increases by accommodating additional strain. The variation in the total plastic strain $(d\varepsilon)$ can be described using a mixture rule between γ and α' [38]: $d\varepsilon = d\varepsilon_{\gamma}(1 - f_{\alpha'}) + \varepsilon_{\alpha'}df_{\alpha'}$. ϵ influences the strain accommodation by modifying $d\varepsilon_{\gamma}$, as it forms by the continuous stacking of dislocation partials. Additionally, since the austenite strength is usually much lower than the martensite, it can also be assumed that there is no plastic deformation in α' , *i.e.* $\varepsilon_{\alpha'} = 0$ [38], giving the relation $\frac{d\varepsilon_{\gamma}}{d\varepsilon} = \frac{1}{(1-f_{\alpha'})}$; this expression shows that strain accommodation in the matrix decreases as the fraction and α' increase promoting the TRIP effect. The strain in the austenite is accommodated by dislocations, ϵ and deformation twins. An ϵ embryo forms by the stacking of single $\frac{1}{6}\langle 112 \rangle$ partials dissociated from $\frac{1}{2}\langle 110 \rangle \{111\}$ perfect dislocations and it can be considered that the strain accommodated by ϵ $(d\varepsilon_{\epsilon})$ is a fraction of the strain accommodated by dislocations $d\varepsilon_{dis}$; since the strain energy of a Shockley partial is $\frac{2}{3}$ the energy of a perfect dislocation, this suggests that the strain accommodated by ϵ ammounts to a similar proportion [39], *i.e.* $d\varepsilon_{\epsilon} = \frac{2}{3}d\varepsilon_{dis}$ is adopted. This gives the relation [16]: $d\varepsilon_{\gamma} = d\varepsilon_{dis}(1 - f_t - f_{\epsilon}) + \frac{1}{\sqrt{2}M}df_t + \frac{2}{3}f_{\epsilon}d\varepsilon_{dis}$, where $\frac{1}{\sqrt{2}M}$ term is the strain accommodated by a twin, and M = 3 is the Taylor orientation factor [40]; rearranging the previous expression it gives $\frac{d\varepsilon_{dis}}{d\varepsilon_{\gamma}} = \frac{1}{(1-f_t-\frac{1}{3}f_{\epsilon})} \left(1-\frac{1}{\sqrt{2}M}\frac{df_t}{d\varepsilon_{\gamma}}\right)$; this shows that dislocation contribution to strain accommodation decreases as the volume fraction of twins and ϵ increase, promoting the TWIP and TRIP effects, respectively. The evolution of ρ can be prescribed in terms of the total strain ε by combining the previous expressions [16]:

$$\frac{d\rho}{d\varepsilon} = \frac{d\rho}{d\varepsilon_{dis}} \frac{d\varepsilon_{dis}}{d\varepsilon_{\gamma}} \frac{d\varepsilon_{\gamma}}{d\varepsilon} = \frac{d\rho}{d\varepsilon_{dis}} \frac{1 - \frac{1}{\sqrt{2M}} \frac{df_t}{d\varepsilon_{\gamma}}}{(1 - f_t - \frac{1}{3}f_{\epsilon})} \frac{1}{(1 - f_{\alpha'})} \\
= \frac{d\rho}{d\varepsilon_{dis}} \frac{1 - \frac{1}{\sqrt{2M}} \frac{df_t}{d\varepsilon} (1 - f_{\alpha'})}{(1 - f_t - \frac{1}{3}f_{\epsilon})(1 - f_{\alpha'})}.$$
(8)

 $\frac{d\rho}{d\varepsilon_{dis}}$ results from the competition between dislocation storage $\frac{d\rho+}{d\varepsilon_{dis}}$ and recovery $\frac{d\rho-}{d\varepsilon_{dis}}$. The latter is given by $f_{DRV}\rho$, where $f_{DRV} = 3.5$ is the dynamic recovery coefficient and this value was adjusted to reproduce the experimental data explored in this work; similar values in austenitic steels have been reported by other authors [16].

When a number of impenetrable obstacles are present, the dislocation generation rate equals [40,41]:

$$\frac{d\rho+}{d\varepsilon_{dis}} = \frac{k_1}{b}\sqrt{\rho} + \sum_i \frac{1}{\Lambda_i b} m_{SF},\tag{9}$$

where the first term accounts for dislocation self-interactions, Λ_i is the mean free path of each obstacle (ϵ and twins) and m_{SF} is the Schmid factor of $\langle 112 \rangle \{111\}$ stacking faults forming from $\langle 110 \rangle \{111\}$ perfect dislocations [25]; $k_1 = 0.06$ is a constant valid for austenitic steels [40, 42]. For the case of hardening induced by deformation bands (ϵ or twinning), previous studies have considered that Λ_i equals [16, 38]:

$$\Lambda_i = \frac{2w_i(1-f_i)}{f_i},\tag{10}$$

where $w_i = r_i^* \hat{N}_i$ is the width of the respective crystal defect. Two assumptions have been introduced in the derivation of equations 9 and 10: 1) the twins or ϵ are fully formed along the grain interiors and 2) no effect of α' forming within the bands is included. However, the length and distribution of the twins and ϵ bands increases with increasing their effective volume $N_i V_i = \frac{f_i}{1-f_{\alpha'}}$ (equation 7), and the first assumption is removed via introducing this prefactor into equation 9. Additionally, since α' grows within the bands, it can be considered that the effective band width w_i decreases according to $1 - f_{\alpha'}$, *i.e.* the factor $(1 - f_{\alpha'})$ is added to Λ_i in equation 9 in order to account for α' formation (assumption 2). The evolution of the dislocation density with strain accommodated by dislocations is given by:

$$\frac{d\rho}{d\varepsilon_{dis}} = \frac{k_1}{b}\sqrt{\rho} + \frac{m_{SF}f_t}{\Lambda_t b(1 - f_{\alpha'})^2} + \frac{m_{SF}f_\epsilon}{\Lambda_\epsilon b(1 - f_{\alpha'})^2} - f_{DRV}\rho.$$
 (11)

This equation shows that the TRIP effect in dislocation hardening is directly influenced by

the ϵ structure (Λ_{ϵ}) ; α' affects the hardening response by replacing the deformation bands and by accommodating additional strain (equation 8). Microstructure evolution and work hardening response can be obtained by solving equations 6, 7, 8 and 11 simultaneously. The flow stress can be estimated using Taylor's formula:

$$\sigma = \sigma_Y + 0.3M\mu b\sqrt{\rho},\tag{9}$$

where $\sigma_Y = \tau_{CRSS} M$ is the yield stress. This equation is employed to obtain the critical strain (at $\tau_i^* = \frac{1}{M} \sigma_i^*$) when ϵ , α' and/or twinning operate; the microstructural feature *i* operates initially if $\tau_i^* < \tau_{CRSS}$.

 σ_Y in polycrystalline austenitic steels is dictated by the friction stress $(M\tau_{nuc})$, solid solution hardening (σ_{ss}) and Hall–Petch effects:

$$\sigma_Y = \left(M\tau_{nuc} + \sigma_{ss} + \frac{k_Y}{\sqrt{D}}\right)G(T, \dot{\varepsilon}),\tag{10}$$

where G is a function of the temperature and strain rate accounting for thermally activated effects altering dislocation glide [40]. A number of models based on thermal activation have been proposed to describe T and $\dot{\varepsilon}$ effects in σ_Y [43]. As this work is focused on describing microstructure evolution considering the yield stress as input, an empirical formula based on Kocks and Mecking model is adopted for the predictions [40]: $G(T, \dot{\varepsilon}) =$ $10.3(\ln \frac{10^7}{\dot{\varepsilon}})^{-0.7}(1.5-3.3\times10^{-4}T-8.9\times10^{-6}T^2+10^{-8}T^3)$, with $G \approx 1$ at room temperature (20 °C) and $\dot{\varepsilon} = 10^{-4}$ s⁻¹ (quasi-static deformation). Solid solution hardening from substitutional elements is very low in austenitic steels [4, 44, 45] and can be considered negligible; however N and C show significant hardening effects in σ_Y [46, 47]; Fleischer's theory is employed to estimate the increment in the critical resolved-shear stress due to the presence of solute atoms [48, 49]: $\sigma_{ss} = (\beta_C^2 x_C + \beta_N^2 x_N)^{1/2}$, where x_C and x_N are the atom fraction of C and N in the steel, respectively, and β_i is the strengthening constant. β_i values have been obtained from experiments: $\beta_N = 1500$ MPa/at [46] and $\beta_C = 1000$ MPa/at [50]. The Hall-Petch constant in austenitic steels (stainless and Mn-containing) has been estimated to lie in the range 450–600 MPa $\mu m^{1/2}$ when the grain size is above ~ 2 μ m [50–52]; $k_Y = 500$ MPa μ m^{1/2} is considered for the present calculations. τ_{nuc} in 316SS has been estimated to lie in the range 70 – 90 MPa [25, 53]; however, the solid solution hardening contribution was not subtracted; it is estimated that the solid solution stress in this is steel is ≈ 60 MPa and $\tau_{nuc} = 15$ MPa is considered for the calculations.

Figure 3 shows a comparison between the predicted and measured yield stress for the alloys considered in Table 1; these conditions cover a wide range in chemical composition and grain sizes to test their contributions to strengthening. Additional experiments for σ_Y at different temperatures, strain rates, and C and N additions are also included; measurements for Fe-20Mn-3Al-3Si (wt %) at different temperatures and strain rates were obtained from [4], where T ranges between -76 °C and 400 °C and $\dot{\varepsilon}$ between 10⁻⁴ s^{-1} and 1000 s^{-1} . σ_Y values for the family FeCrNiMn-(0.24-0.56)N of austenitic steels containing N up to 0.56 wt% were obtained from [47]. Results for the Fe-Mn-Al-C family containing different Mn, Al and C additions are displayed as Fe-(12-30)Mn(0-1.4)Al-(0-1.2)C; these include experimental values for the alloys shown in Table 1 and additional results in Fe-Mn-C alloys with C content up to 1.2 wt% (obtained from [50]); no grain boundary strengthening is considered in the latter, as coarse grains were reported. The model shows very good correlation in the trends with a maximum discrepancy of ~ 75 MPa in the alloy Fe-20Mn-1.2C (wt%). The correlation coefficient is 0.94, indicating that equation 10 reproduces well the experiments. This enables exploring the role of deformation conditions and grain size in the microstructure evolution, via equation 6.

5 Results

The model results for ϵ , α' and twinning are tested against experiments for a number of steels (Table 1); different deformation conditions are considered for each material. The stacking fault energy is a critical input parameter for the models and these values are taken from experiments; γ_{SFE} values at room temperature (20 °C) were obtained from the literature and are shown in Table 2. For the case of Fe16Cr9Ni6Mn1Si, Ulrich *et al.* [54] assumed $\gamma_{SFE} = 26 \text{ mJ m}^{-2}$, however this steel forms ϵ and α' , indicating that the stacking fault energy should be lower. Moreover, Weidner *et al.* [55] have measured

 $\gamma_{SFE} = 17.5 \text{ mJ m}^{-2}$ in a steel with similar composition (Fe-16Cr-6Mn-6Ni in wt %); based on experimental and theoretical studies on alloying effects in γ_{SFE} [56, 57], the additions of 1 wt% Si and 3 Ni wt% in Fe16Cr9Ni6Mn1Si (compared to Fe-16Cr-6Mn-6Ni) should increase the stacking fault energy by $\approx 1.5 \text{ mJ m}^{-2}$, leading to $\gamma_{SFE} = 19$ mJ m⁻²; details of this estimation are shown in Section 6.1. γ_{SFE} shown for 204SS was estimated in [58] using thermodynamic principles. For the case of Fe20Mn3Si3Al no experimental estimations were found. Pierce *et al.* [28] have measured γ_{SFE} in steels with similar composition (Mn in the range 20-24 wt% with different Si and Al content), being in the range of 12–18 mJ m⁻²; $\gamma_{SFE} = 17$ mJ m⁻² was adopted for Fe20Mn3Si3Al. The model results will also be tested at different temperatures and this effect has to be introduced. Remy et al. [59] have determined from experiments in stainless steels that γ_{SFE} has linear variation with temperature in the range 100–600 K; the slope range is 0.04–0.08 mJ m⁻²/K. Miodownik *et al.* [60] found similar slope values in stainless steels in the range 200–400 K. Based on these results, the following relation for the stacking fault energy at different temperatures is adopted for austenitic stainless steels $\gamma_{SFE} = \gamma_{SFE}^{RT} + 0.05(T - 293)$. MATLAB scripts with the solution of all models are included as supplementary material.

The model results for twinning are explored first. Figure 4 shows the predicted and measured twinned structure at room temperature in Fe22Mn0.6C, including (a) average twin width, (b) twin spacing, (c) volume fraction and (d) mechanical response; equation 10 was used in (b). The deformation conditions for this steel are $\dot{\varepsilon} = 5 \times 10^{-4} \text{ s}^{-1}$ and $D = 50 \ \mu\text{m}$; the average twin width is estimated using the relation $\sqrt{\frac{wtt}{2}}$ to account for stereological corrections when measuring the mean width [61]. The model shows very good agreement in (a), (b) and (c), confirming that the microstructure is well described at different length scales, including the nano- and micron-scale twin width and average spacing. The predicted twin width (14–30 nm when $f_t = 0 - 5$ %) is also in agreement with experimental results in Fe-24Mn-0.6C (wt%) obtained in [22]. The flow stress is underpredicted by ~ 150 MPa at $\varepsilon = 50$ %, and this discrepancy can be due to C additions promoting additional strain hardening and other dislocation dissociations, as

previously reported by other authors [30, 50, 62]; additional results in steels with low C will be shown in Figure 7 to support that TWIP effects can be described.

Figure 5 shows the model predictions in 301LN and 304LN, where α' operates. Figures 5(a) and (b) show the volume fraction evolution and flow stress response, respectively, in 301LN at room temperature and different strain rates. The composition of this alloy is Fe-17.6Cr-6.6Ni-1.61Mn-0.48Si-0.22Cu-0.14Mo-0.019C (wt %) and $D = 11 \ \mu m$ [12]. The α' volume fraction at 3×10^{-4} s⁻¹ increases up to 95 % at $\varepsilon = 35\%$, whereas the predicted maximum twin volume fraction is 15% and the maximum fraction of ϵ is 60%. Similar values for twinning and ϵ are predicted at other strain rates. These result indicate that the flow stress response in this steel is controlled by strain-induced α' and ϵ formation (TRIP effect). The model shows very good agreement for $f_{\alpha'}$, confirming that the α' nucleation rate is sensitive to the strain rate (via τ_{CRSS}). The model predicts higher flow stress at higher strains, nevertheless it successfully captures negative strain rate sensitivity observed. The latter can be due to a competition between dislocation forest and stacking fault development; at low strain rates the dislocation generation rate is lower, hence promoting the probability of dislocation dissociation and ϵ formation, whereas at high strain rates a high dislocation interaction rate could prevent forming stacking faults. The discrepancies in the model can be due to the assumption of the constant probability of an α plate to nucleate at the intersection of two ϵ bands not being held at higher strains.

Additional results for $f_{\alpha'}$ in 304LN with composition Fe-18.2Cr-8.1Ni-1.71Mn-0.33Si-0.37Cu-0.32Mo-0.04C (wt%) are shown in Figure 5(c); $D = 5 \ \mu \text{m}$ is reported in this case. The model predicts higher α' fraction by up to 10 %; nevertheless, it successfully captures $f_{\alpha'}$ variation with strain rate; the discrepancies can be due to local variations in the grain orientation [25]. Figure 5(d) shows the α' variation with temperature in 301LN at $\dot{\varepsilon} = 3 \times 10^{-4} \text{ s}^{-1}$. The temperature affects α' formation via γ_{SFE} and τ_{CRSS} ; between -40 °C and 80 °C the former ranges from 11.5 mJ m⁻² to 17.5 mJ m⁻², whereas the predicted values of τ_{CRSS} using equation 14 ($\sigma_Y = \tau_{CRSS}M$) are 126 MPa and 87 MPa, respectively; no experimental values of σ_Y were reported. The stacking fault energy controls mostly microstructure evolution, as $r_{\alpha'}^*$ varies exponentially with γ_{SFE} (equation 3). The model successfully predicts $f_{\alpha'}$ within these temperatures. These results show that the formulation correlates well α' evolution with the flow stress response when the TRIP effect is the main hardening mechanism. Combining the results shown in Figures 4 and 5 will enable describing microstructure and mechanical response in steels where different mechanisms operate simultaneously.

Figures 6(a) and (b) show the predicted and measured volume fraction of ϵ , α' and twinning in 304SS and Fe16Cr9Mn6Ni1Si, respectively; the composition of 304SS is Fe-14.35Cr-8.71Ni-1.93Mn-0.36Si-0.79Cu-0.027C (at%) [3], the grain size is 25 μ m and the stacking fault energy is assumed equal to that for 304LN (Table 2); $D = 20 \ \mu \text{m}$ in Fe16Cr9Mn6Ni1Si. In both cases, the model reproduces the experimental measurements with good agreement; in (a) it is predicted that the fraction of ϵ and twinning increases with strain up to ~ 35-40%; above this strain their fraction decreases due to α' formation. Shen *et al.* [3] observed in this steel that ϵ forms first at low strains ($\epsilon \leq 20\%$), this is followed by twinning ($\varepsilon \leq 30\%$) and α' dominates at strains above $\varepsilon = 30\%$. The predictions are in good agreement with their observations showing that the fraction of ϵ is greater for low strains and it is later consumed by the α' . It is worth noting that very low α' fraction was reported and predicted in 304LN in Figure 5(c), whereas in this case the α' fraction is significantly higher; the difference is due to the grain size being 5 μ m in 304LN reducing significantly the nucleation rate of ϵ and α' , whereas in 304SS $D = 25 \,\mu \text{m}$. In Figure 6(b), the model is able to reproduce the relative variation in ϵ and α' fraction, confirming that the link between the nucleation rate of ϵ and α' proposed in equation 4 is also in agreement with experiments. Although the twinning volume fraction was not reported in this steel, high twinning activity was observed during deformation [3]. Figure 6(c) shows the corresponding flow stress response in 304SS and Fe16Cr9Mn6Ni1Si with the microstructures shown in (a) and (b). The model shows good agreement in the flow stress variation and slope change of 304SS when ϵ , α' and twinning operate simultaneously, however lower flow stress is predicted in Fe16Cr9Mn6Ni1Si; the discrepancies can be due to the activation of secondary slip and twinning systems not considered in the model which can modify the hardening rate, as reported by Ulrich *et al.* [54]. Figure 6(d) shows additional results on the evolution of the twinning volume fraction in Fe20Mn1.2C and Fe17Mn0.56C1.4Al. In both cases the model predicts lower volume fractions, although the relative variation of f_t with γ_{SFE} is consistent. The discrepancies can be due to different dislocation reactions promoting twin formation with high C additions [9]. It has been pointed out that carbon promotes twin formation not only by increasing the stacking fault energy, but also by pinning the dislocation partials and increasing the local stress concentration; the latter aids in promoting the formation of Frank partials, instead of Schockley partials [25], hence modifying the conditions for twin formation and evolution (equations 1 and 6). This effect has not been included in the present model, nevertheless it could be considered in future work.

Another interesting aspect to explore with the model is the role of the grain size and stacking fault energy in microstructure evolution. Figure 7 shows a comparison between the model and experiments for (a) $f_{\alpha'}$ and (b) the flow stress response in 204SS with different grain sizes. The model shows good agreement for low strain levels ($\varepsilon \leq$ 30%), however higher α' fraction was reported at higher strains. Additionally, the model underpredicts σ_Y values by 70 MPa and it estimates lower flow stress response in both cases, although the shape change in the steel with higher α' volume fraction is well reproduced. The discrepancies can be due to the assumption of the probability of an α plate to nucleate at the intersection of two ϵ bands being constant, and the ϵ bands can promote additional strain hardening. Another possibility is due to an inhomogeneous grain or solute distribution, as these alloys were γ -reversion annealed from cold-rolled lath martensite (to obtain different grain sizes); Kisko et al. [34] observed that retained and reverted austenite were present in some testing conditions, altering locally the stability in the austenitic matrix. In order to explore the role of the stacking fault energy in the macroscopic stress response and compare the TRIP and TWIP effects, Figures 7(c) and (d) show the volume fraction and flow stress response in 3 FeMn3Si3Al steels with different Mn contents, respectively. It has been confirmed that TRIP operates in Fe20Mn3Si3Al, TWIP occurs in Fe25Mn3Si3Al, and only dislocation glide is active in Fe30Mn3Si3Al [4] (see Table 2); only the experimental volume fraction of α' in Fe20Mn3Si3Al was reported

in this case. f_t in Fe25Mn3Si3Al is lower than $f_{\alpha'}$ in Fe20Mn3Si3Al, hence inducing lower work hardening; this is confirmed in Figure 7(d). The model reproduces well the relative variation in the flow stress when different mechanisms operate, however it underpredicts the dislocation hardening response in Fe30Mn3Si3Al. The higher measured yield stress and initial work hardening in Fe20Mn3Si3Al can be due to the presence of ~ 20% of thermal ϵ martensite prior deformation, increasing the dislocation/stacking fault activity in the material. The predictions improve as the α' fraction increases, as this initial effect decreases with $f_{\alpha'}$.

6 Discussion

A unified description in the formation of ϵ , α' and mechanical twinning in austenitic steels has been presented. These structures were shown to be formed by hierarchical arrangements of nano-sized embryos. The critical size (r_i^*) and applied stress (τ_i^*) for their formation were obtained by minimising their energy of formation. The only difference between forming an ϵ or twin embryo is in the number of overlapping stacking faults required to form a nucleus. The critical width of an α' plate was considered to be the same as an ϵ embryo, as the latter controls α' formation. The nucleation rate was proposed to be proportional to the critical width, critical resolved shear stress and number density of embryos. The nucleation rate of α' was considered proportional to that for ϵ , following Olson and Cohen's transformation model [19]. These results are consistent with Staudhammer et al. [29] observations, showing that the critical size of an α' embryo did not depend on the deformation conditions and it is only by the applied stress that they form, *i.e.* the deformation conditions affect the nucleation rate only. This analysis is similar to classical nucleation theories based on thermal activation [36], however in this case both r_i^* and $\frac{dN_i}{dt}$ are deformation–controlled. The macroscopic flow stress response was obtained using conventional dislocation theory where twins and/or ϵ bands act as impenetrable obstacles; α' influenced the flow stress by affecting the strain accommodated in the γ and by replacing the ϵ and twin bands as impenetrable obstacles for dislocation slip. Using this formulation it was possible to describe the microstructure and plastic response in

austenitic stainless and high–Mn steels with different initial microstructures and stacking fault energies; good agreement was shown when TRIP and/or TWIP effects operate. The loading direction was considered parallel to the [111] orientation. Nevertheless, the model, in principle, is able to describe orientation effects in the evolution of the microstructure and stress-strain response. For instance, if the results shown in Figures 6(a) and (c) for 304SS are considered in the [001] loading orientation, lower α' , ϵ and twinning activity are predicted by the model. The calculated volume fractions at $\varepsilon = 50\%$ are $f_{\alpha'} = 26\%$, $f_{\epsilon} = 57\%$ and $f_t = 33\%$, whereas the volume fractions shown in Figure 6(a) for the [111] orientation at this strain are $f_{\alpha'} = 55\%$, $f_{\epsilon} = 44\%$ and $f_t = 36\%$. As for the hardening response, the predicted flow stresses at $\varepsilon = 50\%$ in the [111] and [001] orientation are 1690 MPa and 1400 MPa, respectively, showing lower hardening on the [001] orientation. Although the model successfully predicts a decrease in the hardening response due to the lower α' , ϵ and twinning fraction in the [001] orientation, as experimentally observed by other authors [63], effects on dislocation evolution are not included in the model. Adopting additional modelling methods such as crystal plasticity or viscoplastic self-consistent approaches would enable including the effects of orientation, multiple slip and activation of secondary twinning on individual grains.

The model was able to predict partially the evolution of twinning in C-containing TWIP steels. The discrepancies can be due to carbon affecting the dislocation dissociation reactions to form twins. For instance, Idrissi *et al.* [9] observed a high density of sessile dislocations (Frank partials) at the twin bands in a high-C TWIP steel (Fe-20Mn-1.2C wt%), whereas in a C-free steel (Fe-28Mn-3.5Si-2.8Al wt%) very few were observed. Twin nucleation by a Frank partial can occur if it is combined with a Shockley partial and a Cottrell-Lomer (CL) lock, however high local stresses are required for this process to occur [25,64-66]. Karaman *et al.* [25] proposed that this mechanism occurs in a Hadfield steel (Fe-12.34Mn-1C-0.9Si-0.38Cr-0.46Ni wt%) due to the high carbon additions decrease the mobility of the lock and increase the local stress concentrations. Other authors have reached similar conclusions in steels with medium or high carbon content [30,63]. These features can affect the energy balance proposed in equation 1 by including a stress term

promoted by carbon atoms and by modifying the interaction energy between dissociating partials (E_{dis}). This extension can be done in future work. Additionally, the evolution of the total twin volume fraction was considered in this work and possible effects of secondary twinning have not been included explicitly. Nevertheless, it has been shown in previous work that [33], in principle, the model can be extended to account for the individual evolution of secondary and primary twins and account for their respective effects in the work hardening response. This can also be done in future work by accounting for the relevant dislocation dissociation processes and reorientation effects of the primary twins [67].

A number of authors have defined maps showing the regimes where each mechanism operates in terms of the stacking fault energy [1,2]. Although, they provide qualitative insights for their range of operation, their evolution is also controlled by the applied strain [3, 54]. Using this formulation it is possible to explore the effect of the stacking fault energy in the relative activity of ϵ , α' and twinning with different strain levels. Figure 8 shows the variation in volume fraction of these structures for different stacking fault energy values at (a) $\varepsilon = 20$ % and (b) $\varepsilon = 60$ %; the conditions tested for this case are $\dot{\varepsilon} = 10^{-3}$ s⁻¹, T = 20 °C, $D = 20 \ \mu$ m, and no solid solution hardening is considered. The regions where each mechanism dominates, based on previous studies, are also highlighted in (b); the predicted map is in good agreement with these studies. The map differs between low and high strains for γ_{SFE} in the range 16–22 mJ m⁻², where transitions occur. For instance, when $\gamma_{SFE} = 18 \text{ mJ} \text{ m}^{-2}$ the volume fraction of ϵ and twinning increase rapidly in (a) (~ 20 %), however these structures transform into α' as the strain increases in (b). Similarly, when $\gamma_{SFE} = 20 \text{ mJ m}^{-2}$, f_t and f_{ϵ} have similar values in (a) (~ 12-15 %), however the twin volume fraction increases rapidly up to 70 %as the strain increases. These results are in agreement with the predicted microstructures for the steels explored in the previous section: α' dominates in 301LN and 204SS due to their low γ_{SFE} (Table 2), whereas ϵ , α' and twinning operate jointly in 304SS and Fe16Cr9Ni6Mn1Si as they have intermediate γ_{SFE} values. Twinning is the dominating mechanism in Fe20Mn1.2C, Fe22Mn0.6C, Fe17Mn1.4Al0.6C and Fe25Mn3Si3Al, whereas

dislocation glide is only present in Fe30Mn3Si3Al. It is also possible exploring how the chemical composition affects the occurrence of these mechanisms if the stacking fault energy is known.

6.1 Alloying contributions to microstructure evolution

The main contribution of alloying additions to microstructure evolution is through the stacking fault energy. γ_{SFE} values were obtained from experimental measurements and remained fixed for a given composition. It is interesting exploring how the microstructure changes when modifying alloying additions from a base composition. Several studies on alloying effects in the stacking fault energy have been performed using various experimental techniques, thermodynamic principles, and atomistic simulations [56, 57, 68–70]. Although, there is significant scatter between predicted and measured values for wide compositional ranges, linear relations between composition and γ_{SFE} exist for small compositional variations. Thus, the stacking fault energy can be approximated by:

$$\gamma_{SFE} = \gamma_{SFE}^0 + \sum_j \alpha_j (x_j - x_j^0), \qquad (11)$$

where γ_{SFE}^0 and x_j^0 are the stacking fault energy and atom fraction of the alloying element j in the base alloy and x_j is the atom fraction of the variant composition. Effects of Ni, Mn, Si and Cr in austenitic stainless steels are explored and Table 3 shows the coefficients employed in this work which have been obtained by other authors. α_{Ni} in Table 3 is valid only when adding up to 12 wt%, whereas α_{Mn} is valid when Ni content is in the range 8–10 wt%.

Figure 9(a) and (b) show the effect in the volume fraction and flow stress response, respectively, in 304SS with 3 Ni additions (8.3, 9 and 12 wt%). The stacking fault energy for the base composition is considered equal to 304LN and the predicted values for the remaining alloys are 19.4 mJ m⁻² and 24.8 mJ m⁻². The model shows good agreement in the variation of $f_{\alpha'}$ and flow stress with stacking fault energy. Figures 9(c) and (d) show the variation in α' volume fraction in 301SS at different temperatures and at $\varepsilon = 30$ % when modifying (c) Si and Mn and (d) Ni and Cr simultaneously; the experimental results were obtained from [71]. In this case, the stacking fault energy for the base composition (Fe-17.34Cr-7.03Ni-1.07Mn-0.48Si-0.11C-0.02N wt%) is assumed to be 14.7 mJ m⁻² (Table 2); specific compositional variations for each condition can be found in [71]; the model shows good agreement in the trends for all temperatures in (c), however it predicts lower $f_{\alpha'}$ values when increasing/decreasing Ni/Cr content in (d); the discrepancies can be due to Cr affecting the contribution of Ni to the stacking fault energy [57]; this has not been included in equation 11. Nevertheless, the results show that the model is sensitive to compositional variations if they are captured properly in the stacking fault energy. These results also show that different mechanisms can be tailored when modifying alloying additions. For instance in 304SS (assuming base composition Fe-18Cr-8Ni0.33Si wt% and $\gamma_{SFE} \approx 17.8$ mJ m⁻²), increasing Si or Cr to 0.96 wt% and 20.8 wt%, respectively, promotes α' formation and the TRIP effect ($\gamma_{SFE} \approx 15$ mJ m⁻²), whereas increasing Ni up to 10.5 wt % reduces the formation of ϵ and α' , promoting the TWIP effect only ($\gamma_{SFE} \approx 22$ mJ m⁻²). This framework could be applied to alloy design for TRIP/TWIP effects if alloying effects are considered in γ_{SFE} .

7 Conclusions

- A unified description for the evolution of ε- and α'- martensite, and twinning in austenitic steels was presented. These results, combined with dislocation-based descriptions, were applied to describe microstructure and flow stress response in steels where TRIP and/or TWIP operate. The description was able to capture the competition between different microstructural features in stainless and high-Mn steels.
- The evolution of micron-scale ϵ and twin bands were obtained by describing a hierarchical arrangement of nano-sized ϵ and twins (embryos). The critical size and applied stress when these structures form were obtained by minimising the free energy of formation. The only difference between forming an ϵ plate or a twin was in the number of overlapping stacking faults. The evolution of twinning in TWIP steels with medium/high-carbon was underpredicted; a reason for this can be due

different dislocation reactions occurring by the presence of carbon atoms, altering the critical energy for twin nucleation. These features can be explored more in detail in the future.

- A nucleation rate equation was proposed in terms of the critical embryo size, resolved shear stress and number density. The nucleation rate of α' was considered proportional to the rate of ϵ nucleation. This criterion was consistent with Olson and Cohen's transformation model [19].
- Mechanism maps showing the operation range of *ε*, *α'*, and twinning in terms of the stacking fault energy were identified at different strain levels. Deformation temperature and chemical composition effects in microstructure were explored via modifying the stacking fault energy.
- The role of chemical composition in austenitic stainless steels was explored, showing that TRIP and TWIP effects can be promoted in the same alloying system. For instance in 304SS, increasing Si or Cr to 0.96 wt% or 20.8 wt%, respectively, promotes α' formation ($\gamma_{SFE} \approx 15 \text{ mJ m}^{-2}$), whereas increasing Ni up to 10.5 wt% promotes TWIP effect only ($\gamma_{SFE} \approx 22 \text{ mJ m}^{-2}$). This shows that the present work can be applied to alloy design for TRIP/TWIP effects.

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Steel	Ni	Mn	Si	Al	С	Ν	Cr	Cu	Author
301SS	6.6–9.2	0.5 - 1.6	0.15 - 0.88	-	0.02	0.09 - 0.12	15.9 - 18.7	0.22	[12, 71, 72]
304SS	8-12	1.7	0.33 - 0.72	-	0.02 - 0.06	0.05 - 0.1	18.3	0.4 - 0.79	[3, 6, 12, 45, 72]
Fe16Cr9Ni6Mn1Si	8.85	5.56	0.96	-	0.05	0.06	15.75	-	[54]
204SS	1.1	9	0.4	-	0.079	0.115	15.2	1.68	[34]
Fe17Mn1.4Al0.6C	-	17.5	0.24	1.4	0.56	-	-	-	[73]
Fe20Mn1.2C	-	20	-	-	1.2	-	-		[74]
Fe20Mn3Si3Al	-	20	3	3	-	-	-		[4]
Fe22Mn0.6C	-	22	-	-	0.6	-	-		[75]
Fe25Mn3Si3Al	-	25	3	3	-	-	-		[4]
Fe30Mn3Si3Al	-	30	3	3	-	-	-		[4]

Table 1: Chemical composition (in $\mathrm{wt\%})$ of the steels tested in this work.

Steel	$\gamma_{SFE} {\rm ~mJ~m^{-2}}$	Author
301SS	14.7	[12]
304SS	17.8	[12]
204SS	16.8	[58]
Fe16Cr9Ni6Mn1Si	19	[54, 55]
Fe20Mn1.2C	20	[74]
Fe17Mn1.4Al0.6C	27	[69]
$\rm Fe22Mn0.6C$	22	[75]
Fe20Mn3Si3Al	17	[4]
Fe25Mn3Si3Al	21	[28]
Fe30Mn3Si3Al	40	[76]

Table <u>2</u>: Values of the experimental stacking fault energy.

$\alpha_j \ (\mathrm{mJ} \ \mathrm{m}^{-2}/\mathrm{wt}\%)$	Author
1.8	[57, 77]
-0.9	[77]
-1.5	[70]
-4	[69]
	-0.9 -1.5

Table 3: Stacking fault energy parameters

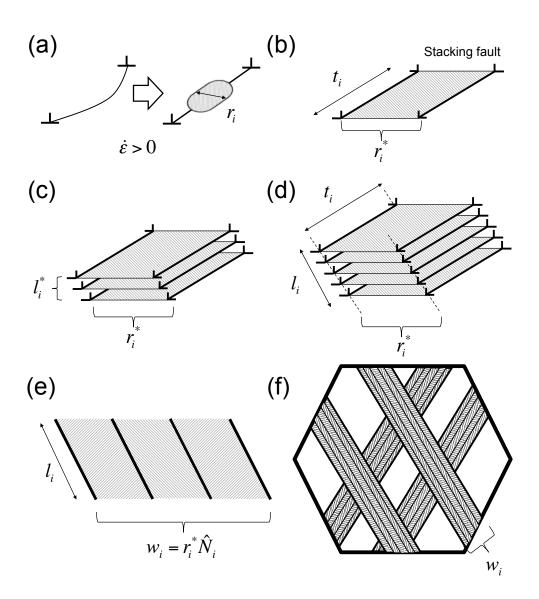


Figure 1: Schematic representation of the proposed mechanism of ϵ and twin formation.

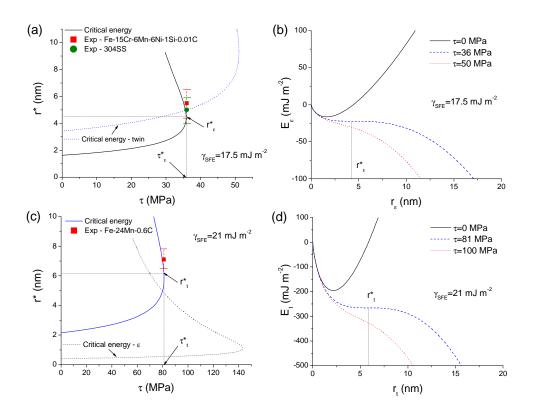


Figure 2: (a) Critical ϵ width vs applied stress. (b) Free energy variations with ϵ width for different stress levels. (c) Critical nano-twin width vs applied stress. (d) Free energy variations with nano-twin width for different stress levels.

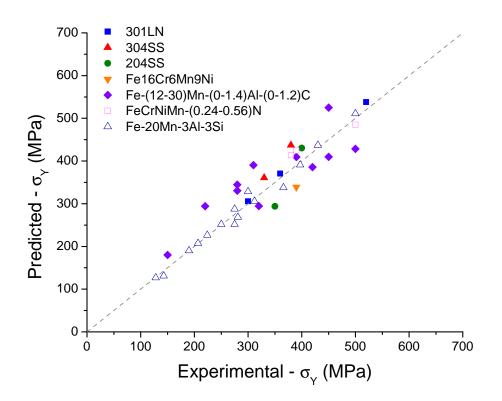


Figure 3: Experimental vs predicted yield stress.

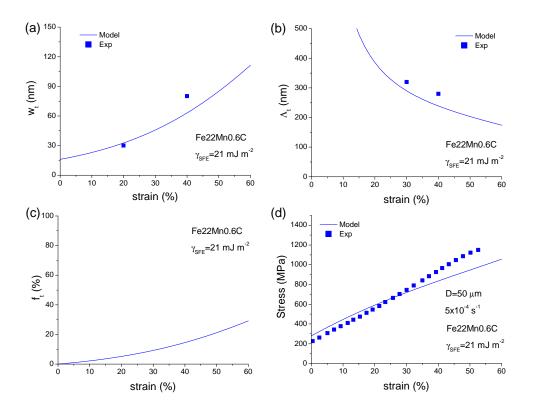


Figure 4: Predicted twinned structure in Fe22Mn0.6C including average twin (a) width, (b) spacing, (c) volume fraction and (d) flow stress response.

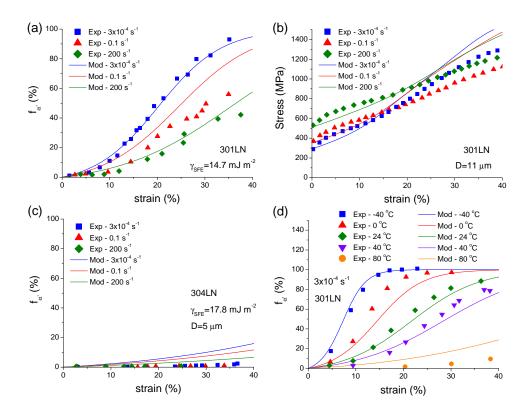


Figure 5: Predicted α' evolution in 301LN for different strain rates, including (a) volume fraction and (b) flow stress. (c) α' evolution in 304LN at different strain rates. (d) Temperature effects on $f_{\alpha'}$ in 301LN.

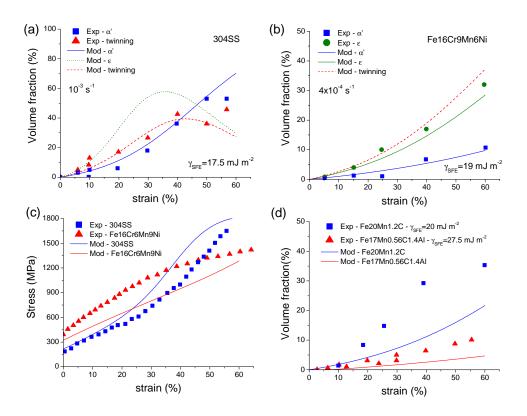


Figure 6: Microstructure evolution in (a) 304SS and (b) Fe16Cr9Mn6Ni1Si when ϵ , α' and twinning operate, and (c) their respective mechanical response. (d) Twin volume fraction in C-containing TWIP steels when only twinning operates.

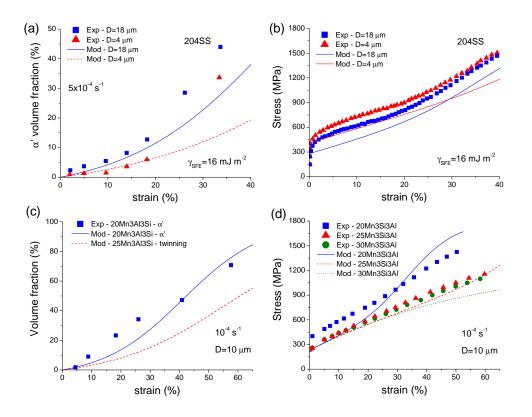


Figure 7: (a) α' evolution and (b) flow stress response in 204SS with different grain sizes. (c) Microstructure evolution and the corresponding (d) flow stress evolution in Fe-(20-30)Mn3Si3Al.

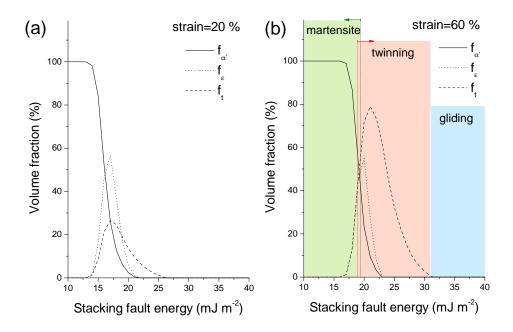


Figure 8: Variation in the volume fraction of α' , ϵ and twinning for different stacking fault energies at (a) $\varepsilon = 20$ % and (b) $\varepsilon = 60$ %.

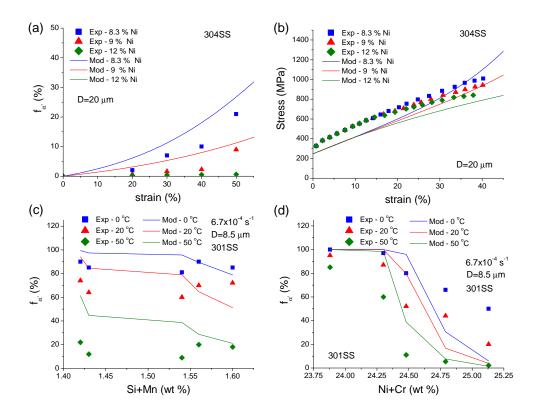


Figure 9: (a) α' fraction and (b) flow stress in 304SS with different Ni contents. α' fraction in 301SS when modifying simultaneously (c) Si and Mn and (d) Ni and Cr.