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Effect of Vortex Generators on Corner Separation Caused by Shock Wave-Boundary-Layer Interaction

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Wind tunnel experiments were conducted to investigate the effect of vortex generators on a transonic corner flow separation, resulting from the interaction of a normal shock wave with a turbulent boundary layer in a duct at $M = 1.4$. The shape of the vortex generators was rectangular. The vortex generators were mounted on the bottom wall of the test section. The investigation studied the effects of the rotation direction of the vortex, the VG size and position relative to the shock and the walls. When the leading edge of the vortex generators turn towards the corner, the effect of the vortex generators on the corner flow separation monotonically decreased as the vortex generators size reduced. In these cases, it was observed that independent separations appeared on the bottom wall. When the leading edge of the vortex generators points in the opposite direction away from the corner, the flow structure was found to depend on the size and the location of the vortex generators. We categorized the flow structures into three modes. The effect of the vortex generators and the three modes were successfully collapsed with a location parameter normalized by the second power of the non-dimensional size.

Nomenclature

- $A_v$ = angle of a vortex generator to the uniform flow
- $D_{vl}$ = distance between a side wall and the leading edge of a vortex generator
- $D_{vt}$ = distance between a side wall and the trailing edge of a vortex generator

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†Professor, Department of Engineering. Associate Fellow AIAA.
$H_v =$ height of a vortex generator

$L_v =$ length of a vortex generator

$M =$ Mach number of uniform flow

$P =$ Static pressure

$P_0 =$ Stagnation pressure

$Re =$ Reynolds number

$T_0 =$ Stagnation temperature

$W_{1B} =$ Width of the streamlines at $x = -60$ mm on a bottom wall for an evaluation $W_{2B}$

$W_{2B} =$ Local minimum width of the streamlines starting from $W_{1B}$ on a bottom wall

$X_{vs} =$ location of vortex generators in the streamwise direction

$x =$ streamwise direction

$x_v =$ distance from the leading edge of a vortex generator in the streamwise direction

$y =$ vertical direction to a bottom wall

$z =$ spanwise direction

$z_v =$ distance from the leading edge of a vortex generator in the spanwise direction

$\Delta X_{vs} =$ distance between a normal shock wave and the leading edge of a vortex generator

$\delta =$ thickness of the boundary layer at the leading edge of a vortex generator

Subscripts

$NoVG =$ No vortex generator condition

I. Introduction

On a wing in a transonic flow, harmful separations are caused by shock wave-boundary-layer interactions especially on the off-design conditions. Figure 1 schematically shows such separations on a passenger aircraft wing. Generally, a strong shock wave appears on the midspan because the local Mach number in this area is higher than elsewhere. This shock wave can cause the midspan separations which may lead to the transonic buffet [1]. In addition, a corner flow separation can appear in the wing-body junction [2] because the viscous retardation of the body and the wing surfaces leads to significant loss of streamwise momentum in the corner [3].
Previous research [4,5] shows that the vortex generators (VGs) work well to reduce midspan separation on the backward swept wing when the leading edge of the VGs turns towards the wing tip. On the other hand, VGs were found to have little effect on the wing when the leading edge turns towards the wing-body junction. In this paper, we refer to the former direction as “toe-out” and the latter direction as “toe-in”.

The objective of this research is to determine the potential of VGs to reduce the corner flow separation in the wing-body junction. In this region, it is not immediately clear that “toe-out” VGs will be more effective because of the particular flow field they generate. Figure 2 schematically shows the boundary layer downstream of a VG placed ahead of a normal shock. On the downwash side of the vortex, the thickness of the boundary layer is decreased by the vortex as expected. However, the thickness of the boundary layer increases on the upwash side [6]. This is caused by the low momentum flow transported from the downwash side. Thus, a separation can appear on the upwash side when a shock wave interacts with this thickened boundary layer. Therefore, this project investigates the influence of VG direction on the reduction of corner flow separation. Furthermore the influence of VG size and location is also studied.

The aim is to arrive at recommendations for the placement of VGs on a wing as illustrated in Fig. 1. In order to answer this question and to extract the dominant flow physics, we simplified the problem from a real wing-body junction to the corner of a rectangular duct as shown in Fig. 3. Although real wing-body junctions are rounded or chamfered to alleviate the corner separation, we selected the sharp corner in order to not complicate the problem. We decided to concentrate on the more fundamental physics of transonic corner flows. It is suggested that any benefits of flow control observed in this simplified canonical problem would also successfully address corner flow separation in rounded
corners. Therefore, the information of this research might allow designers to reduce the degree of rounding off or address situations where corner separation prevails even in cases where the junction is already rounded or chamfered.

Fig. 2 Flow structure downstream of a VG with a shock wave.

Fig. 3 Simplification of wing junction problem from a real aircraft to a duct.

II. Experimental method

A. Wind tunnel and shock holding system

Experiments were performed in the Cambridge University Engineering Department supersonic wind tunnel no.1. Figure 4 shows a schematic figure of the flow field and the test section. To hold the normal shock wave at a specific location, a shock holding plate was set in the test section [7]. By adjusting a choking block mounted on the shock holding plate at the exit of the test section, the normal shock wave can be fixed at the plate’s leading edge. The distance
between the shock holding plate and the bottom wall was 122 mm. The width of the duct was 114 mm. A right-handed coordinate system as shown in Fig. 4 is used in this paper. The origin of the coordinate system is on the center line of the bottom wall at the nominal shock position.

![Fig. 4 Experimental setup.](image)

Table 1 summarizes the inflow conditions. The nominal Mach number and total pressure were set at 1.4 and 185 kPa, respectively. Total temperature was 300 K ± 5 K. The unit Reynolds number is calculated at 27.4 million. Typical duration time of each blow was about 20 seconds.

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<th>$P_0$ [kPa]</th>
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<td>27.4 million</td>
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**B. VG parameters**

Figure 5 shows the geometry of the VGs used in this study. We defined VGs whose leading edge turns towards the corner as “toe-in”, and VGs whose leading edge points in the opposite direction as “toe-out”. The VGs were mounted on the bottom wall in all test cases. The shape of the VG was rectangular. The main parameters were height $H_v$, length $L_v$, angle $A_v$, and the distance from the side wall $D_{vl}$ and $D_{vt}$. Here, the parameters $D_{vl}$ and $D_{vt}$ are the distance from the side wall to the leading edge and to the trailing edge of the VG, respectively. The boundary layer thickness at the leading edge of the VG $\delta$ was adopted as the representative viscous length-scale. This was estimated from a straight line interpolation of the velocity profiles given in Ref. [8]
Table 2 and 3 show the parameters of all test cases. In the baseline VG tests, the VG parameters were equivalent to those used in previous research [4,5]. Such VGs were found to successfully reduce transonic buffet on wings. In line with previous research, the height of the VGs was 1.6 times the thickness of the boundary layer at $x = -100$ mm which is the baseline case VG position. The distances between the VGs and the sidewall, $D_{vl}$ and $D_{vt}$ are one of the parameters varied in this research. In the baseline cases, the distances were selected to avoid any interaction between the VGs and the sidewall boundary layer. The minimum distance between the VGs and the sidewall is 7.5 mm, which is 1.6 times the boundary layer thickness in the base VGs case. The aspect ratio of the VGs $L_v/H_v$ and the angle $A_v$.
were fixed at 4 and 20 degrees, respectively. To investigate the influence of the VG size, heights of 2.5 mm and 5.0 mm were also tested. The influence of VG location was investigated only in the toe-out cases.

### Table 2 Parameters of toe-in VG

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<tr>
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<th>$L_v$</th>
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<th>$\Delta X_{vo}$</th>
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### Table 3 Parameters of toe-out VG

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C. Measurement techniques

A schlieren system is used to monitor the flow fields. The system consisted of a light source, two concave mirrors, a reflection mirror, a knife edge and a CMOS camera. A circular area of diameter 203 mm is visualized by the system through the observation windows. The direction of the knife edge is set in the horizontal direction to best visualize the VG’s vortex. Although this is sensitive to vertical density gradients, the normal shock wave can be clearly seen because of the shadowgraph effect.

Surface oil flow is used to visualize the streamlines on the bottom wall and sidewall at $z = +57$ mm. The mixture uses a combination of Titanium Dioxide (TiO$_2$) powder, fluidic paraffin, and oleic acid. The ratio of the TiO$_2$ and the fluidic paraffin is 33 g to 175 ml. About 10 drops of oleic acid is added after mixing.

A two component Laser Doppler Velocimetry (LDV) system (TSI) is used for velocity measurements. Two pairs of coherent laser beams (542nm and 532nm) are focused inside the test section. The measurement volume is 130 μm in diameter. Kerosene particles with a diameter of approximately 0.5 μm [8], are used as the tracer. The measurement volume is traversed from $y = 20$ mm to $y = 0$ mm at $x = +40$ mm and $z = -47$ mm. The velocity measurements are...
repeated three times. Although typical measurement accuracy was estimated to be better than 1 m/s [9], a larger discrepancy is locally observed between the three measurements because the seeding density in the measurement location is locally lower than ideal. To illustrate this discrepancy, the images in the results section will include data from all runs. Finally, the typical uncertainty (95% confidence interval) is estimated as less than 15 m/s. Only for the toe-out VG case, the uncertainty is locally higher than others in the region higher than $y = 7$ mm. Here, this uncertainty is estimated as 33 m/s.

To calculate the local Mach number from the velocity data, total temperature is measured by T-type thermo couples in the settling chamber. The local Mach number at each measurement point is calculated from the total temperature and the measured velocity. An adiabatic flow is assumed in the calculation. Considering error propagation, the total uncertainty of the local Mach number is better than 0.1 throughout (including the worst regions discussed above). The uncertainty except for the worst region is better than 0.05.

Total pressures and wall static pressures are recorded using a pressure scanner. The uncertainty of the pressure scanner is less than 0.1 kPa.

The pressure distributions on the bottom wall are also visualized with pressure sensitive paint (PSP). The PSP (UniCoatPSPUNC-12, ISSI) is painted directly on the metal surface of the bottom wall. The PSP is illuminated with UV light (LM2x-DM, ISSI) through the observation window. The luminescence of the PSP is recorded with a consumer CMOS camera (Nikon D7100) at a resolution of 0.04 pixel/mm. After an intensity correction, a Wiener filter is applied to the images to reduce the influence of noise. A window size of 64 pixels $\times$ 64 pixels is adopted for the procedure corresponding to 2.4 mm $\times$ 2.4 mm in physical length. In-situ calibration technique with linear Stern-Volmer equation [10] is adopted to change the intensity ratio of the images to the pressure value. Six taps on the center line of the bottom wall are used as the reference points. The root mean square of the difference between the PSP data and the pressure scanner data is roughly 5% of the measurement values.

III. Results

A. Influence of the VG direction

Figure 6(a) shows a schlieren image in the no VG case. The location of the normal shock wave is adjusted to be at $x = 0$ mm. The choking block is then fixed at this position for all other cases. Because of the interaction between the normal shock wave and the boundary layer, a $\lambda$ shock wave appears in the region close to the bottom wall. The height of the triple point is about 20 mm.
Figure 6(b) shows a schlieren image for the baseline toe-in VG case. The location of the normal shock wave is $x = 10$ mm which is further upstream than in the no VG case. The size of the $\lambda$ shock wave is larger than in the no VG case and the height of the triple point is about 40 mm. This indicates that a larger separation appears on the bottom wall compared to the no VG case. **The leading leg of the $\lambda$ shock wave is more blurred than that in the no VG case.** The schlieren images are the result of a spanwise integration of the density gradient information. In addition, they include all information in the exposure time. Thus, the blurred shock wave indicates that the separation on the bottom wall could be more ununiform and unsteady in the baseline toe-in VG case compared to the no VG case.

Figure 6(c) shows a schlieren image of the baseline toe-out VG case. The location of the normal shock wave is a little upstream from in the no VG case. The size of the $\lambda$ shock wave is smaller than in the no VG case. The height of the triple point is less than 20 mm. This indicates that the toe-out VGs reduce the size of the separation on the bottom wall. **The leading leg of the $\lambda$ shock wave is more distinct than that in the no VG case.** This indicates that the separation on the bottom wall could be more uniform and steady than in the no VG case.

![Schlieren images of the normal shock wave](image)

(a) No VG  
(b) Toe-in VG  
(c) Toe-out VG

Fig. 6 Schlieren images of the normal shock wave in the no VG case, the toe-in VGs case ($H_v = 7.5$ mm, $D_v = 7.5$ mm, $\Delta X_{sv} = 100$ mm) and the toe-out VGs case ($H_v = 7.5$ mm, $D_v = 7.5$ mm, $\Delta X_{sv} = 100$ mm).

Figure 7(a) shows the oil flow visualization for the no VG case on the sidewall and the bottom wall. In the no VG case, flow separations are observed in both corners. The streamlines on the bottom wall show attached flow in the center region.
Figure 7(b) shows oil flow pictures for the toe-in VG case. From the streamlines on the sidewall, it is confirmed that the VGs reduce the corner flow separation. The angle of the streamlines from \(y = 25\) mm to 50 mm on the sidewall is lower than that in the no VG case. However, a separation appears in the center region on the bottom wall. We will refer to this as the “bottom wall separation” hereafter. The bottom wall separation in Fig. 7(b) corresponds to the separation on the compression side of the vortex in the single VG case discussed earlier (see Fig. 2).

Figure 7(c) shows oil flow pictures for the toe-out VG case. From the streamlines on the bottom wall, it is confirmed that the VGs reduce the corner flow separation on the bottom wall. The toe-out VGs lift the low momentum flow from the corner and onto the sidewall. As the result, a new separation independently appears on the sidewall. We will refer to this as the “sidewall separation” hereafter.
Fig. 7 Oil flow pictures in the no VG case, the toe-in VGs case ($H_v = 7.5\text{mm}, D_{vl} = 7.5\text{mm}, \Delta X_v = 100\text{mm}$) and the toe-out VGs case ($H_v = 7.5\text{mm}, D_{vt} = 7.5\text{mm}, \Delta X_v = 100\text{mm}$).

Figure 8 shows the profiles of local Mach number in the vertical direction at $x = +40\text{mm}$ and $z = -47\text{mm}$. The values are calculated from the velocity profiles measured with LDV. The measurement location is illustrated as an open circle in Fig 7. From $y = 0\text{mm}$ to $5\text{mm}$, the local Mach numbers in the VG cases are higher than that in the no VG case. These results quantitatively confirm that the VGs accelerate the flow close to the bottom wall at this measurement point. From $y = 10\text{mm}$ to $20\text{mm}$, the local Mach number in the toe-out VG case is lower than that in the no VG case. The low speed region is caused by the sidewall separation shown in Fig. 7(c).

Fig. 8 Local Mach number distribution downstream of the normal shock wave ($x = +40\text{mm}, z = -47\text{mm}$).
Figures 9(a)-(c) show the pressure distributions on the bottom wall measured with PSP. In the toe-in VG case, a low-pressure region extends from the VGs to downstream of the normal shock wave. These low pressure regions are thought to be foot prints of the streamwise vortices caused by VGs. The pressure distribution in the corner regions is more complex in the toe-in VG case because of the influence of these vortex footprints. The shape of the shock wave on \(xz\) plane is approximately estimated from the pressure distribution in the toe-out VG case. It seems that the shock wave in the toe-out VG case is more straight than that in the no VG case.

The symbols and lines in Fig. 10 show the pressure measured by pressure taps and PSP, respectively, along the center line of the bottom wall. The pressure increase location in the toe-in VG case is the most upstream of all three cases. This is likely caused by the bottom wall separation. It can also be seen that the toe-out VG case shows a slightly increased pressure recovery after the shock.
As mentioned above, both the toe-in and the toe-out VGs work well to reduce the corner flow separation. However, both VG types also cause additional separations on the bottom wall for toe-in VGs and the sidewall for the toe-out VGs. Thus, if toe-in VGs were placed on a wing to control wing-body junction flow, an undesirable additional separation might result. Therefore toe-out VGs would be preferable in such a scenario, because the flow on the fuselage is usually less critical. Since the adverse pressure gradient on the body is generally weaker than that on the wing, we can expect that the influence of the sidewall separation is minimized. In the following, the influence of size and location will be studied for toe-out VGs mainly.

B. Influence of VG size and location

Figures 11(a) and (b) show the oil flow pictures when the height of VGs are 5.0 mm and 2.5 mm, respectively. As shown in Figs. 11, the sizes of the vortex and the bottom wall separation decrease gradually as the size of the toe-in VGs reduces. Their influence on the flow field monotonically reduces as the size decreases.
On the other hand, the flow structure can change dramatically with reducing the toe-out VG size. Figure 12(a) shows oil flow pictures for the smallest toe-out VG case (height: 2.5 mm). The location of the leading edge of the VG is the same as that in Fig. 7(c). In Fig. 12(a), the sidewall separation does not appear. Instead, the size of the corner flow separation is increased compared to the no VG case as seen from the surface flow on the bottom wall. Because the vortex scale in Fig. 12(a) is smaller than that in the baseline toe-out VG case, the expected separation on the compression side of the vortex locates at lower position comparing with the baseline toe-out VG case. As the result, the expected separation is not isolated but rather adheres to the corner flow separation which is consequently increased.

To investigate the influence of VG location, the smallest VG is moved further upstream to $x = -200$ mm. Figure 12(b) shows the oil flow pictures for this case. The interval between the VG and the sidewall is the same as previously. From the oil flow on the bottom wall, it can be confirmed that the corner flow separation is reduced and that an independent sidewall separation can be observed in the top figure of Fig. 12(b).

The influence of the interval between the VG and the sidewall is also investigated. In these cases, the height of the VGs is 7.5 mm. The location of the VGs in the streamwise direction is fixed at $x = -100$ mm. Figure 13(a) shows the oil flow for the largest interval case. The interval between the trailing edge of the VGs and the sidewall is 22.5 mm. In this case, an independent sidewall separation does not appear in the same way as in Fig. 12(a). Instead, the size of the corner flow separation increases from the original size. Thus, once again, the expected separation on the compression side of the vortex adheres to, and enlarges the corner separation.
Figure 13(b) shows the oil flow pictures for the smallest interval case. The interval between the trailing edge of the VG and the sidewall is 0 mm. For this condition, the pattern on the bottom wall doesn’t differ greatly from that in Fig. 7(c). However, the side wall separation is largest of all toe-out VG cases. It appears that this condition should be avoided in practical situations.

![Oil flow pictures of the toe-out VGs](image)

**Fig. 13 Oil flow pictures of the toe-out VGs ($H_v = 7.5$ mm, $\Delta X_v = 100$ mm).**

### C. Categorization of the separation modes

Since we observed several different separation behaviors, we categorized the separation into different ‘modes’ based on an observation of the oil flow pictures. Figure 14 summarizes these separation modes.

The toe-in VG cases are simply grouped into the “influence mode” and the “no influence mode”. When the size of the toe-in VGs decreases, the influence of the toe-in VGs on the corner flow decreases but there is no drastic change to the flow structure.

On the other hand, the separation behavior in the toe-out VG cases can be categorized into three modes. In the first mode, the sidewall separation appears independently. The size of the corner flow separation is reduced by the streamwise vortex. We name this first mode the “lift off mode” because the low momentum flow in the corner region is lifted off to a high position on the sidewall. In the second mode, the corner flow separation increases from the base flow case. The sidewall separation does not appear in this mode. We name this second mode the “adhesion mode” because the low momentum flow on the compression side of the vortex adheres to the corner flow separation. The second mode appears when the VG size decreases and the interval between the VG and the sidewall increases from
(a) Tree diagram of categorization

Fig. 14 Categorization of the separation modes.
the condition in the lift off mode. The third mode is termed the “no influence mode”. In this mode, the vortex does
not interact with the corner flow separation. The bottom wall separation appears independently as shown in Fig. 2.

D. Quantitative evaluation of the VGs effect from oil flow pictures

Since the lift off mode is desirable for the reduction of corner flow separation, it would be useful to determine the
criteria governing the transition boundaries between the separation modes. To obtain those and quantitatively evaluate
the effect of the VGs from the oil flow pictures, we introduce a parameter, \( W_{2B} \) as shown in Fig. 15. We select two
streamlines at \( x = -60 \text{ mm} \). One streamline is the symmetry line (\( z = 0 \text{ mm} \)) while the other is closer to the corner by
a spanwise distance \( W_{1B} = 47 \text{ mm} \). This is chosen because a streamline at this position (10 mm from the side wall)
generally remains clearly visible whereas streamlines closer to the corner are often difficult to identify. Following
both streamlines in flow direction generally shows that there is a minimum separation distance \( W_{2B} \) where the corner
separation is greatest. Thus, any changes in the local minimum width can be used as a measure of the effect of VGs
on the corner separation size.

![Fig. 15 Definition of \( W_{2B} \) for quantitative evaluation of VGs effect.](image)

Figure 15 shows the influence of VG location on \( W_{2B}/W_{2B,\text{NoVG}} \) for all cases except for the case with zero interval.
Here, \( W_{2B} \) is normalized with the value in the no VG case, \( W_{2B,\text{NoVG}} \). The oil flow visualizations suggest that the
separation mode changes from the adhesion mode to the lift off mode when the location parameter \( \Delta X_{vs}/D_{vt} \) increases.
The lift off mode is observed when the VG height is greater than or equal to the boundary layer thickness, and the
parameter \( \Delta X_{vs}/D_{vt} \) is higher than thirteen. In the lift off mode, the value \( W_{2B}/W_{2B,\text{NoVG}} \) decreases with increasing
distance \( \Delta X_{vs} \) between the shock wave and the VGs. It seems that the decrease is a consequence of the boundary layer
development after the vortex passes through the corner region. When the height of the VGs is lower than the boundary
layer thickness, \( W_{2B}/W_{2B,\text{NoVG}} \) is lower than in the other cases. Figure 16 clearly shows the influence of the VG size.

To summarize the influence of the size and location of the VGs on \( W_{2B}/W_{2B,\text{NoVG}} \) and the separation mode, we
normalized the location parameter \( \Delta X_{vs}/D_{vt} \) with the second power of the non-dimensional VG size \( H_v/\delta \) as seen in Fig.
17. This seems to successfully collapse the influence of the VGs size. The boundary between the two separation modes
is at about \((\Delta X_{vo}/D_{vo})(H_v/\delta)^2 = 14\). Below this value, \(W_{2B}/W_{2BNoVG}\) increases dramatically. After that, \(W_{2B}/W_{2BNoVG}\) decreases gradually.

Fig. 16 Relation between the evaluation \(W_{2B}/W_{2BNoVG}\) and the VGs location parameter, \(\Delta X_{vo}/D_{vo}\) \((L_v/H_v = 4, A_v = 20\text{ deg})\).

![Fig. 16 Relation between the evaluation \(W_{2B}/W_{2BNoVG}\) and the VGs location parameter, \(\Delta X_{vo}/D_{vo}\) \((L_v/H_v = 4, A_v = 20\text{ deg})\).

Fig. 17 Relation between the evaluation \(W_{2B}/W_{2BNoVG}\) and the location parameter corrected by the VG scale, \((\Delta X_{vo}/D_{vo})(H_v/\delta)^2\) \((L_v/H_v = 4, A_v = 20\text{ deg})\).

![Fig. 17 Relation between the evaluation \(W_{2B}/W_{2BNoVG}\) and the location parameter corrected by the VG scale, \((\Delta X_{vo}/D_{vo})(H_v/\delta)^2\) \((L_v/H_v = 4, A_v = 20\text{ deg})\).]

It seems that the location of the sidewall separation is determined by the upper edge of the vortex. Hence, we hypothesize that the separation mode becomes the lift off mode when the upper edge of the vortex penetrates the corner boundary layer in the region upstream of the shock wave. In addition, we hypothesize that the separation condition is similar for the bottom wall when the vortex upper edge is the same location even if the VG’s parameters are different. Therefore, we non-dimensionalize the location parameter \(\Delta X_{vo}/D_{vo}\) with the second power of the non-dimensional VG size \(H_v/\delta\). The normalization with the second power of the scale parameter is based on the ideas shown in Fig. 18 relating both vortex size and trajectory to VG height. In the flow field, the vortex scale and the vortex trajectory are influenced by the scale parameter \(H_v/\delta\). When the height of the VG increases, the size of the vortex
increases almost proportionally. However, a scale correction of the trajectory is not so obvious because the trajectory is influenced by both the strength of the vortex and the distance between it and its mirror vortex. The vortex strength increases as the VG size increases. However, the distance between the real and the mirror vortex also increases as the VG size increases and therefore both effects contradict each other. Thus, we investigated the trajectory of two single vortex cases, for two heights of VGs.

![Diagram](image)

Fig. 18 Concept of VG scale correction for the non-dimensional parameter \( \frac{\Delta x_v}{D_v}(H_v/\delta)^2 \).

Figure 19 shows the trajectories of the vortex footprint. The height of the small VG and the large VG are 2.5 mm and 7.5 mm, respectively. As shown in Fig. 19, the trajectory of the small VG is in good agreement with that of the large VG when they are both normalized with \( H_v/\delta \). Hence, it seems that the idea in Fig. 18(b) is appropriate. As the result, the normalization works quite well as shown in Fig. 17.

![Diagram](image)

Fig. 19 Vortex trajectory and corrected trajectory with the non-dimensional VG size \( H_v/\delta \)
Figure 20 shows the relationship between the parameters in Fig. 17 and a typical wing-body junction problem. An ideal vortex trajectory is also shown in Fig. 20, where vortex interacts with the corner flow just upstream of the shock wave. In order to avoid a detrimental interaction between the VG and the boundary layer on the body, the interval $D_{vt}$ should be larger than the boundary layer thickness on the body. If the aspect ratio and the VG angle are in the range tested in this research, an optimum height and location of VGs can be determined based on the boundary of the separation modes in Fig. 17. Because, in the lift off mode, the sensitivity of the VG effect is low to the normalized location parameter, it seems that the parameter should be selected conservatively. For example, we propose to start practical tests at a value, $(\Delta X_{vs}/D_{vt})(H_{v}/\delta)^{2} \cong 40$.

Wind tunnel experiments were conducted to investigate the effect of vortex generators (VGs) on a corner flow separation caused by an interaction between a normal shock wave and a turbulent boundary layer in a Mach 1.4 flow. We defined VGs whose leading edge turns towards the corner as “toe-in VG”, and VGs whose leading edge points in the opposite direction as “toe-out VG”. The VGs were attached on the bottom wall of the test section. The influence of the VG direction, the size, and the location on the corner flow separation was investigated mainly based on surface oil flow visualization.

It was found that toe-in VGs whose height was about 1.5 times the boundary layer thickness reduced the corner flow separation when the interval between the VG and the sidewall was the same as the VGs height. However, at the
same time, a large separation appeared in the center region on the bottom wall. The influence of the toe-in VGs monotonically decreased as the VGs size reduced.

The effect of the toe-out VGs was categorized into three ‘modes’ namely, the “lift off mode”, the “adhesion mode”, and the “no influence mode”. The lift off mode was effective at reducing the corner flow separation. However, in this mode, a large additional sidewall separation was also observed. The effect of the VGs decreased in the lift off mode with increasing distance from the shock wave. The area of the corner flow separation clearly increased in the adhesion mode.

We defined the ratio of the distance from the shock wave to the distance from the side wall as the location parameter. We also defined that the ratio of the VG height to the boundary layer thickness as the scale parameter. The effect of the toe-out VGs and the separation modes were successfully collapsed with the location parameter normalized by the second power of the scale parameter. Based on these results, we proposed optimum parameters for toe-out VGs to reduce the corner flow separation.

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References


