

## **Metal Transfer and Wear**

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### **Introduction.**

These thoughts are offered as a reminder that Tribology is not all about the normal contact of fractal surfaces, and indeed, not all about elastic contact of rubber and polymers, or even about dry contact. Machines do still contain metal surfaces sliding past each other, hopefully separated by an oil film; and sometimes, when tolerances have been pushed too far, or running with starved lubrication when the oil or grease supply is inadequate, with some metal to metal contact. Fortunately this is not always disastrous: surfaces do often run-in, so that after running with contact and a contribution of dry-contact friction, there is steady wear and contacts no longer occur. The traditional design criterion for gears and ball races was, and still is, the  $\Lambda$  – ratio : the ratio of the predicted film thickness for smooth surfaces to the rms roughness. Certainly a  $\Lambda$  – ratio of 3 or more<sup>1</sup> usually leads to full-film lubrication: but to anyone with the slightest background in surface roughness this is an absurd rule. Assuming, as is usually done, that the predicted smooth-surface film thickness refers to the distance between the mean planes of the roughness, the rms roughness says nothing about the how much contact there will be. And if running-in is successful, and the high points of the surface wear away, the rms (and the  $\Lambda$  – ratio ) may hardly change, but there will be successful operation.

But when will running-in be successful? What determines when instead of running-in there will be scuffing, and disaster?

The traditional picture of the “mixed friction” regime is that when the local film thickness falls to zero, additives (or perhaps happy accidents) provide a boundary lubricant in the oil: some form of long chain polymer, which has a reactive end which attaches itself to the metal, and carries the load on its free ends: with low friction but, more importantly, preventing metal to metal contact. The Blok scuffing criterion was that the maximum surface temperature must be below a specific value: and there was the problem, what should it be? In Bowden & Tabor’s laboratory experiments, using a known, pure, organic compound, clear links with the known properties could be found; but in engineering practice perhaps all that can be done is to ensure that the calculated maximum temperature in a new application is no more than in an existing application: the ISO guide concentrates on the temperature calculation, not on the temperature found.

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<sup>1</sup> The “traditional” requirement is  $\Lambda > 3$ . But see Cann(1994), or Greenwood(2020) for alternatives.

But what happens when boundary lubrication fails? Fortunately it seems that we do not move completely into the dry wear scenario. The failure will usually be local, and the dry wear process interrupted. An earlier work (Sakman et al (1944)) reported that in a pin on disc experiment, flooding the surface with a plain mineral oil halved the transfer at a light load, but produced only a small reduction at a heavier load. But flooding with oleic acid largely eliminated transfer. Here it seems desirable to review what has been learnt about dry wear, and, perhaps, forgotten.

### **Transfer and wear.**

The obvious starting point is the “Archard” wear equation. This was predicted by Holm in 1938, by postulating that for every encounter of a pair of atoms (within the contact area found as  $W / p_m$ ) there was a fixed probability of one being pulled out of its parent surface. Detailed experimental confirmation was provided by Burwell & Strang (1938), but from electron micrographs of transfer particles they argue that the unit event is the encounter of two asperities. Both models predict that the volume of wear  $V$  is proportional to the distance slid  $L$  and the load  $W$ , and inversely proportional to the hardness  $p_m$ :  $V = k \cdot L \cdot (W / p_m)$ . Archard’s contribution was to show that it is not necessary to assume that the average size of the contact areas or wear particles is constant, and to calculate the probabilities  $k$  implied by the results of all the available experimental wear combinations...and to go on to contribute to the great wear research program of Hirst’s group at AEI (Associated Electrical Industries) Aldermaston (see Archard (1953), Kerridge (1955) etc.)

### ***Wear of soft steel against hard steel.***

The natural meaning of the term “wear” is the weight, or volume, lost from the device concerned: and early researchers merely noted that this could become either transfer particles attached to the “wrong” partner, or loose wear debris. The important distinction between transfer and wear was first made when Kerridge (1955) found that when a (radioactive) steel pin was loaded against a rotating hard steel ring (“hollow drum” perhaps conveys the picture), a radioactive transfer layer built up on the ring, but the radioactivity (and therefore the amount of transfer) then became constant. When the active pin was replaced by an inactive one, the activity reduced, mirroring the path of the increase: it was not that the transfer layer had a maximum size, and could build up no further, but that a steady state had been reached where the transfer to the ring equalled the rate of loss from the ring. At this point the pin wear rate fell to the steady rate required by the wear law. The wear fragments were carefully collected and monitored, little radioactivity being found at first, but ultimately matching the wear rate of the pin: and consisting of relatively large, *oxidised*,

particles. The detachment of the transfer layer, and so presumably its oxidation rate, was the rate-determining process. Experiments in air at  $10^{-3}$  mm mercury found the wear rate reduced to a tenth (or lower at low loads) of the atmospheric value, confirming this.

Thus, for this combination, wear is a multi-stage process. First, metallic transfer from pin to ring as submicroscopic particles. These are then smeared out to form a (harder) transfer layer. The transfer layer then oxidises, helped by the temperature produced by frictional heating, weakening its attachment to the ring, and finally the oxidised layer is rubbed off as large oxide particles to form the wear debris.

### ***Wear of brass against hard steel (severe wear).***

Kerridge & Lancaster (1956) followed this by replacing the soft steel pin by an irradiated (60/40) brass pin. Initially both wear of the pin and transfer increased exponentially at almost the same rate, with nothing left over to form wear fragments. When the experiment was repeated with a load  $5\times$  higher but lubricated with cetane, the same was true, but the amounts reduced to one quarter. The significant feature was that as the transfer film reached its limiting value, the wear rate fell to its uniform rate. As in Kerridge's experiments, when the active pin was replaced by an inactive one, the decrease from the limiting activity rate to zero mirrored the growth from zero to limiting activity. And when an inactive pin was replaced by an active one, there was at first no activity in the wear debris: *wear particles are not produced directly from the pin*. Convincing evidence was given that individual wear particles at a given time after a pin replacement all had the same activity, ie each had the same mix of "new" and "old" transfer fragments.

The authors emphasize that the term "transfer film" is misleading; the transfer layer is composed of identifiable fragments. These grow by accretion of further fragments to become incipient wear particles, perhaps  $50\times$  larger than the transfer fragments, before becoming detached as wear particles. But the fragments are themselves much larger than the likely size of asperity contacts, more approximating to "the total real area of contact as estimated from the ratio of the load to the flow pressure of 60/40 brass", so it seems (although the authors do not quite say this) that incipient transfer fragments form *on the pin* by accretion from individual intermetallic junctions.

Thus, for this combination, wear is again a multi-stage process: first, transfer fragments are assembled on the pin, which then transfer from pin to ring, and then become larger by accretion: these are smeared out to become harder, thicker, flakes, which finally become detached as wear particles.

The authors, rather as an aside, report that both the transfer rate and the wear rate are proportional to the load, and that the same applies to the *sizes* of transfer fragments and wear particles: concluding that "*the number of individual events occurring . . . is the same at all loads*". This is a flat

contradiction of the Archard (and Greenwood!) belief, that the typical event is the same at all loads, and that only the number of events is proportional to load.

The authors also make the very perceptive remark (in view of the work of Cocks and Antler to be described below), “Once a fragment has been transferred to the ring, the load will be concentrated on that fragment during subsequent passages beneath the pin”.

### **Wear of hard steels against hard steel (mild wear)**

One might expect mild wear to be the more straightforward process, but this was not what Archard & Hirst (1956) found. When rubbing hardened tool steel pins against a disk of the same material, the initial behaviour was as described above, (but on a scale two orders of magnitude less): the pin wore by transfer to the disk, the transfer fragments then aggregated into larger (metallic) fragments which became detached as wear particles. But as the conformity between pin and disk improved, many of the transferred fragments were worn away by a much smaller scale process. And then in a final stage the wear rate increased by a factor of five, and seems to have occurred as abrasion by large (oxidised) wear particles. At this stage the transfer “layer” consisted of areas with no transfer and patches very much thicker than the average (50 to 100Å) thickness.

### ***Wedges (prows).***

Tribologists have long regretted the impossibility of directly examining the area of contact between sliding metals: but in 1962 two researchers reported the results of looking sideways at the contact<sup>2</sup>..which “of course” could reveal nothing. But it did!

When Cocks(1962) loaded a hemispherically ended copper rider against the surface of a rotating large cylindrical copper drum (load 700g, speed 0.038cm/sec) he found: *“This immediately revealed some unexpected phenomena. Most of the time during sliding, the drum and rider were separated by a wedge of displaced metal which emerged from the drum surface and became trapped between them”*

The same was found for other metal pairs. Rider and drum were polished up to grade 0000 paper, and then cleaned to be wettable by water and yielding a high coefficient of friction (1.1 to 1.4). The rider was given a slight transverse movement to avoid repeating the same path on the drum.

*A wedge of metal displaced from the drum becomes trapped between the two sliding members and holds them apart. Thus, the drum surface slides against the wedge instead of the rider itself. As the sliding proceeds, the wedge continuously receives more metal from the drum. At the same time fragments of metal from the wedge are intermittently redeposited back on the drum, and can be seen emerging from the contact on the drum surface. From time to time the wedge itself breaks away from the rider, and is carried away on*

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<sup>2</sup> Cocks reported some preliminary results in 1958, (cited by Antler (1962)) so undoubtedly has priority

the drum surface. However, when this happens a new wedge immediately begins to form and the surfaces are soon visibly separated again.

Neither the hardness, nor the relative hardnesses of rider and drum appeared to matter.

The whole assembly of rider, wedge and part of the drum could be mounted in a cold-setting plastic without ever separating them, and then sectioned, polished and etched. Figure 1 shows a result. The wedge is initiated by transfer from the drum, and remains bonded to the rider. It is "a relatively compact mass of metal, not an aggregate of individual fragments . . .". The wedge grows by accretion, at the front, where "*the material of the wedge is continuous with that of the drum*": so the relative motion must cause shearing of the metal, presumably rather similar to what happens in the formation of a chip in the machining of a ductile metal.

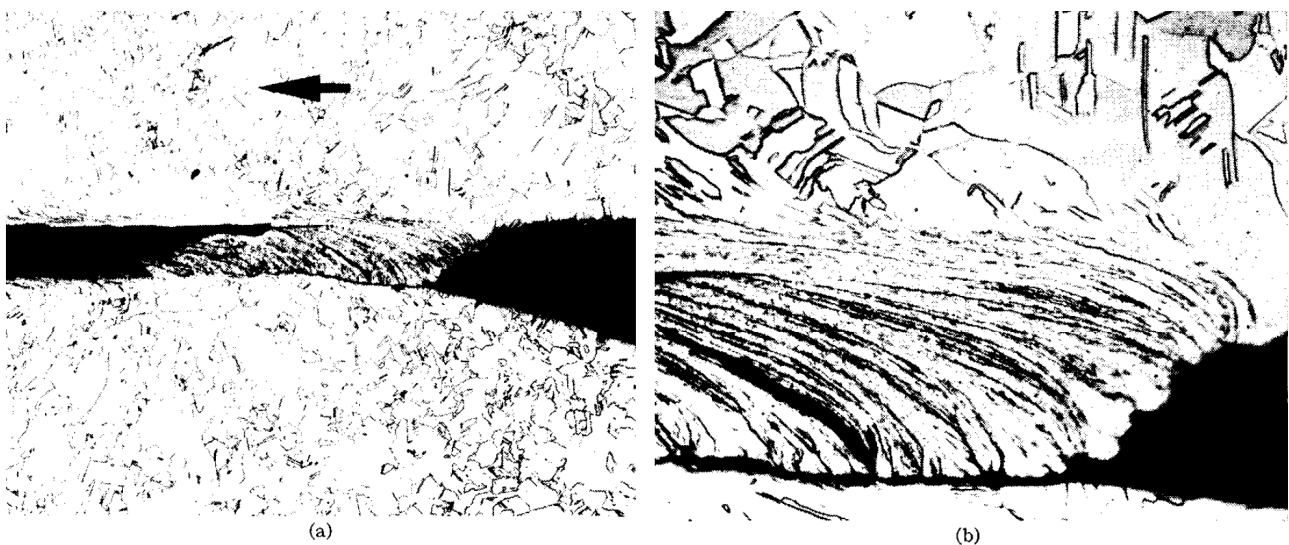


FIG. 5. Section through the wedge and adjacent parts of the drum and rider after sliding at a speed of 0.038 cm/sec with a load of 710 g. Drum and rider of oxygen-free high-conductivity copper. (a) Complete wedge. Magnification 100X. (b) Right-hand portion of the section in Fig. 5(a). Magnification 340X.

**Figure 1** Wedge linking drum and rider. (reproduced from M. Cocks, Journal of Applied Physics 33 , 2152 (1962) with the permission of AIP Publishing)

The life of a wedge is very variable: as short as 20 sec (sliding distance 0.8cm): often 10 to 20 min (sliding distance 25 to 45 cm) and sometimes longer. After perhaps 1 min it seems an equilibrium size is reached where continued accretion at the front is balanced by fragments breaking off from the rear. (And sometimes the entire wedge breaks away.)

Cocks(1964) showed that the wedge formation and consequent separation of the sliding bodies occurs in the same way between two flat surfaces, usually with several wedges in action at once. The wedge may be formed by accretion from either disk, and occasionally (see one beautiful micrograph of a wedge formed by a pair of SAE1020 steel disks at 5kg load) by accretion at both ends. These later experiments showed that the wedge mechanism seemed able to continue

indefinitely (copper on copper), to reduce to a much smaller scale (steel on steel), or apparently to cease completely (nickel on nickel).

Antler(1962), working with metals suited to electrical contacts, mostly using lighter loads (100g) and longer runs (40m sliding distance) found similar behaviour. He emphasises the irrelevance of the relative hardnesses of rider and flat, and how the prow (his term, but also “wedge-shaped prow”) becomes very much harder than either, making its resemblance to a machining tool clearer. But he gives many examples of the complexity of the process: one example being for a gold rider sliding on a palladium flat:

- (a) First pass: gold rider deposits adherent particles on palladium flat with little palladium transfer to gold;*
- (b) Second and third passes: rider removes gold from flat;*
- (c) Subsequent passes: a severely work hardened gold prow gouges [the] flat, producing palladium particles that adhere to the rider;*
- (d) From this point, sliding is identical to the all-palladium system, regardless of length of run. Practically all debris is palladium.*

Note the hardnesses: Gold, 79 kg/mm<sup>2</sup> " ; Palladium, 142 kg/rnm<sup>2</sup>: but it is the soft gold which wears away the hard palladium!

Antler(1964) notes that *wear by the prow-formation mechanism tends to change to the rider-wear severe regime on prolonged sliding in the same track. This was observed with a variety of metals, including aluminum, copper, gold, palladium, and silver sliding on themselves.* This differs from what Cocks reports for his pin on disc experiments, but he never ran on the same track.

### **Rabinowicz's Contribution**

The first use of radioactivity to study transfer was when Sakmann et al (1944) slid an inactive slider over an activated block, and measured the transfer with a Geiger counter. Gregory (1946) slid a radioactive lead slider<sup>3</sup> over an inactivated flat surface: this permitted the use of autoradiography to study the transfer. He noted average film thicknesses between 10 and 100 lead atoms thick.

Rabinowicz & Tabor (1951) modestly state:

*This paper describes an extension of Gregory's autoradiographic method to a study of the friction and pick-up occurring between stationary and sliding metal surfaces in the absence and in the presence of lubricant films.*

carrying understatement too far! They established the proportionality between pick-up and load: that for like metals there was no correlation between pick-up and hardness: that for dissimilar metals the pick-up was typically less by a factor 50, mainly due to the smaller size of the transfer fragments, typically 10<sup>-8</sup> g

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<sup>3</sup> A lead slider containing a radioactive isotope (of radon?); by implication all that was available in Australia at the time

compared to  $10^{-6}$  g . They conclude that *metallic transfer does not occur as a uniform smear but as a relatively small number of discrete fragments*

which seems to be the first clear statement of this fact<sup>4</sup>. But sadly for the present purpose, the main thrust of the paper is to study the effect of lubrication, certainly on both friction and transfer, but really hoping to get some clue to the origin of friction.

However, Rabinowicz & Tabor make the important discovery that transfer takes place under purely normal loading, although on a much reduced scale, with transfer fragments typically  $10^{-11}$  g : still enormous by atomic standards ( $10^{10}$  atoms). Rabinowicz (1952) followed this up more carefully, finding the total transfer (copper to copper: load 4kg) of  $3 \times 10^{-8}$  g to  $3 \times 10^{-9}$  g, but falling to  $10^{-10}$  g when great care was taken to avoid lateral motion.

Are such transfer fragments consistent with an atom by atom transfer process?

We note with interest Rabinowicz (1953) “A quantitative study of the wear process” –which is entirely about transfer fragments, with no mention of wear fragments! However, following Kerridge and Kerridge&Lancaster, Rabinowicz (1958) recognised the distinction between transfer and wear , and propounded a criterion for the size of wear fragments (The AEI publications contain estimates of the sizes of transfer and wear fragments, but make no attempt to predict them) . Rabinowicz starts from the basic Bowden & Tabor idea of a lump of metal torn out of the base and crushed against the slider so that it adheres and becomes a transfer fragment. When the crushing load is removed, the fragment relaxes, but remains stretched because it adheres to the slider, and residual stresses remain. A fragment of volume  $V$  with mean residual stresses  $\bar{\sigma}_r$  will have a strain energy  $(\bar{\sigma}_r^2 / 2E) \cdot V$  . Rabinowicz explain that to separate the transfer particle from the slider involves the creation of new free surface, so for an area  $A$  and a work of adhesion  $w_{ab}$  for the pair of materials will require an energy  $A(w_{ab})$  : the first introduction of surface energy into Tribology<sup>5</sup>. Thus, the minimum size of loose wear fragments will be when

$$(\bar{\sigma}_r^2 / 2E) \cdot V = A(w_{ab}) . \text{ Accordingly, for a hemispherical fragment of radius } r , \text{ we must have}$$

$$r \geq (3E / \bar{\sigma}_r^2) \cdot (w_{ab}) .$$

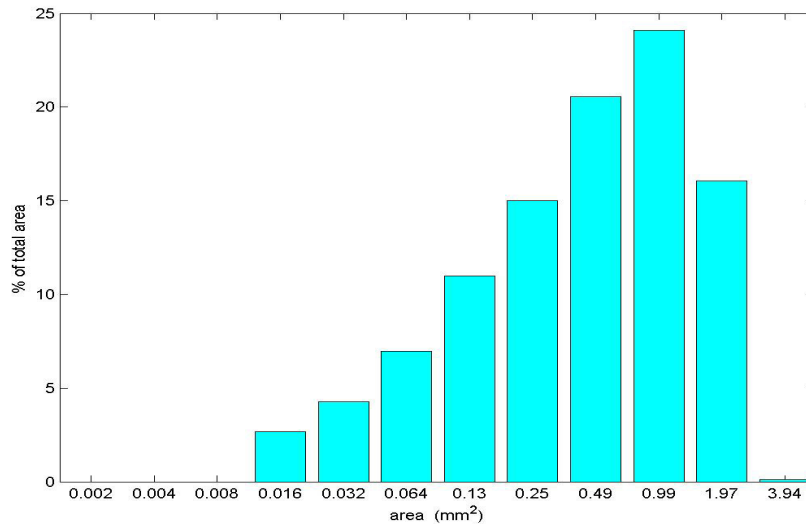
The maximum possible strain energy density is  $Y^2 / 2E$  where  $Y$  is the yield stress in tension, and clearly the mean residual stress after unloading will be less. Rabinowicz (1958) suggests that the strain energy might be perhaps 10% of the maximum possible. (In his 1961 paper, he suggests residual stresses are often found to be  $\sigma_r = \nu Y$  , which when Poisson’s ratio  $\nu = 0.3$  gives 9%).<sup>6</sup> He goes on to argue that for most metals the elastic strain at yield may be taken as  $3 \cdot 10^{-3}$  , so sets  $Y / E = 3 \cdot 10^{-3}$  , and takes  $Y = p_m / 3$  where

<sup>4</sup> But sliding was not completely steady, with some stick-slip. Did this matter?

<sup>5</sup> Or should one count Deryaguin’s (1933) estimate of the force of adhesion?

<sup>6</sup> I find these estimates hard to accept: stresses of order  $Y$  may well be found near the interface, but will these not be very local?

$p_m$  is the hardness, so a simplified, practical criterion is  $r \geq 30,000 (w_{ab}) / p_m$ . But in wear tests to confirm this, he switches from the predicted *minimum* fragment size to the “*average*” size (total weight of larger particles equals total weight of smaller ones): despite some scatter, the agreement is reasonable. But what then do we deduce about the origin of the multitude of smaller fragments contributing half the total weight? The size distribution of the wear fragments is not given, but the Kerridge & Lancaster paper described above, and figure (2) shows their results.



Figure(2) Size distribution of wear particles for brass pin sliding on hard steel (load 22.5Kg).

There is no evidence *in these experiments* of a minimum size for wear particles. And it should be noted that in experiments in which active and inactive pins were interchanged, individual wear fragments had different specific activities: ie each particle contained a mixture of active and inactive atoms. No particle has a life history like that postulated in the Rabinowicz model.

## Discussion.

We all know that the underlying problem in studying wear is the multiplicity of wear mechanisms. Even when considering a given materials pair, as the mild wear of hard steel against itself as studied by Archard & Hirst (above) or gold against platinum as described by Antler, there was a sequence of different mechanisms. Challen & Oxley (1979) used a slip-line field solution to model the steady motion when a hard slider traversed a rigid/perfectly plastic half-space, and found three modes of deformation; ( 1) plastic flow of the surface by a wave pushed ahead of the slider, referred to by Challen & Oxley as “rubbing mode”; (2) a deformed ‘prow’ which becomes detached from the surface; (3) a cutting mode in which a ‘chip’ is continuously cut from the surface. Kayaba et al (1986) refer to all three as abrasive wear: the rubbing mode, rather inappropriately, as ploughing (though they do sometimes find a gentle trace). They experimented with a hard steel pin against brass, mild steel and stainless steel. All three combinations, when unlubricated, show each of the



three modes, as the parameter  $\sqrt{W/R^2 H_V}$  (where  $R$  is the pin radius,  $H_V$  the hardness and  $W$  the load) increases. They show scanning electron micrographs of prow formation (with no reference to Cocks or Antler), and similar pictures for steel against brass, where the prow material passes under the slider and becomes a chip. When lubricated with a smear of silicone grease, with the two steels all three modes are found: however lubricated brass gave just two modes: the rubbing mode at higher loads but changing at light loads to *flaking*: the flakes then forming wear debris. This appears to be the delamination wear mode studied by Suh (1973), and caused by incremental plastic flow as the Challen & Oxley plastic wave moves over the surface and produces below the surface an *almost* reversible plastic strain cycle. I cannot resist including his conclusion (Suh 1988) “(2) *The wear rate of metals may be predicted in the near future, based on first principles and fundamental material properties.*”

And of course these are just a few wear mechanisms: one should certainly add metallographic phase transformations (Welsh(1965) and his demonstration that increasing the load or speed not only changes wear from mild to severe, but, because of the frictional temperature rise, there are “*three transitions: (1) a change from mild to severe wear at relatively light loads ( $T_1$ ): (2) a change from severe wear back to mild wear at higher loads, ( $T_2$ ): (3) a perturbation in the mild-wear rate at even higher loads, ( $T_3$ ) with the wear rates of the pin and ring diverging.*”)

Others emphasise the development of subsurface cracks, or tribochemistry, or simple corrosion.

I have confined my attention to the largely forgotten classic contributions.

For they are largely forgotten. Exceptionally, deRoos and colleagues (2001,2013) know of Cocks and Antler’s work, so are able to build on it in their investigation of how hard transfer fragments build up on a deep-drawing tool and ruin the finish. In contrast, a recent admirable paper (Tarasov et al 2017) studies the sliding of a hard steel pin on an aluminium disk. Their interest is in Friction Stir Welding, so they contribute new information about the effect of temperature on the iron/aluminium combination: but they rediscover prow formation, the formation of a transfer layer, and back transfer to the disk — all without noticing that it has been discovered already 60 years ago. But no radiography, so they do not learn that transfer particles are formed by accretion over time, not torn out bodily as lumps.

Is it all right to forget all this, because prows and riders are just examples of Godet’s “Third Body”, so need not be treated separately? There seems no doubt that Antler’s “riders” are indeed third bodies. It is less clear that Cocks’ prows are: certainly sometimes they are the very opposite: they are the link which makes the first and second bodies into one! There are not two bodies sliding past each other: there is a single body shearing along a neck. It seems clear that the formation of transfer layers is not a three body process: and the transfer layer is not itself a third body any more than the oxide film can usefully be treated as such: perhaps there has been insufficient study of the five-body problem, where debris particles on their way out of the conjunction roll about between two oxide films?

Yes, study the behaviour of trapped particles: but if all transfer and wear is attributed to third bodies, the term has become too wide to be useful. But at least stop studying the purely normal contact of rough surfaces.

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